

1/46

FIG. 1

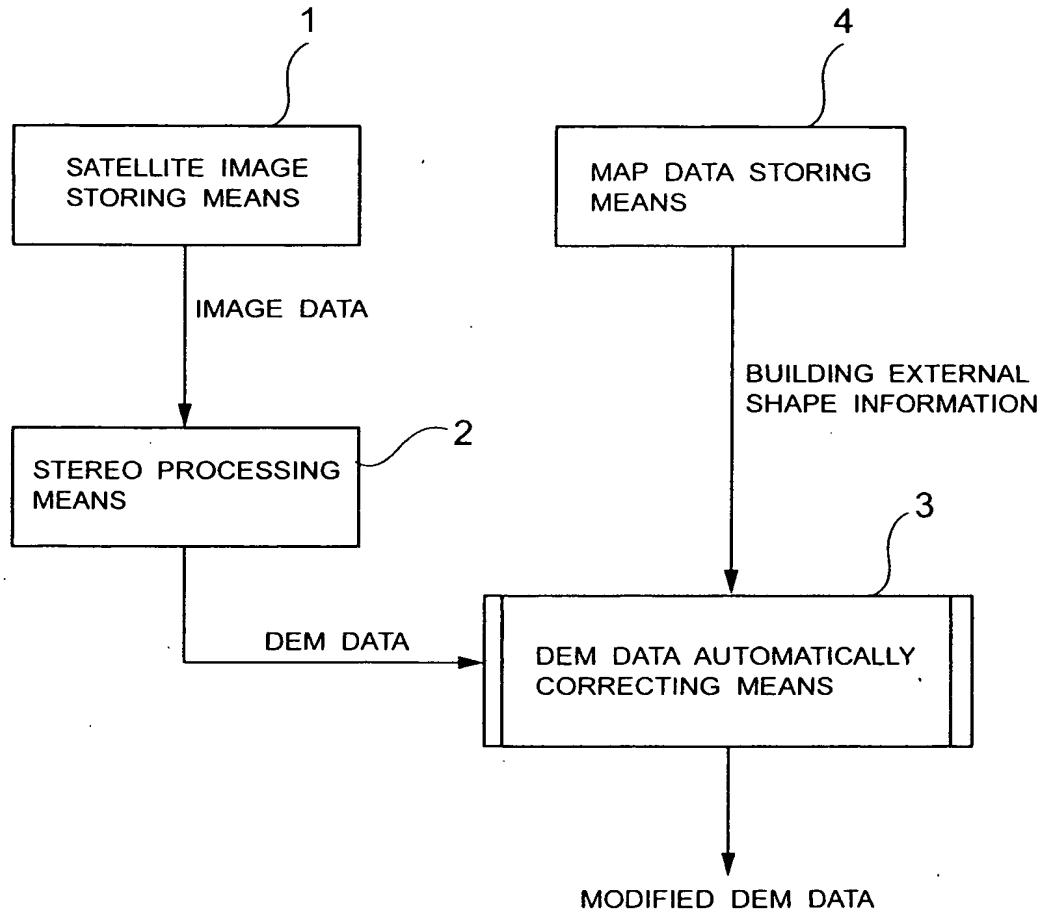
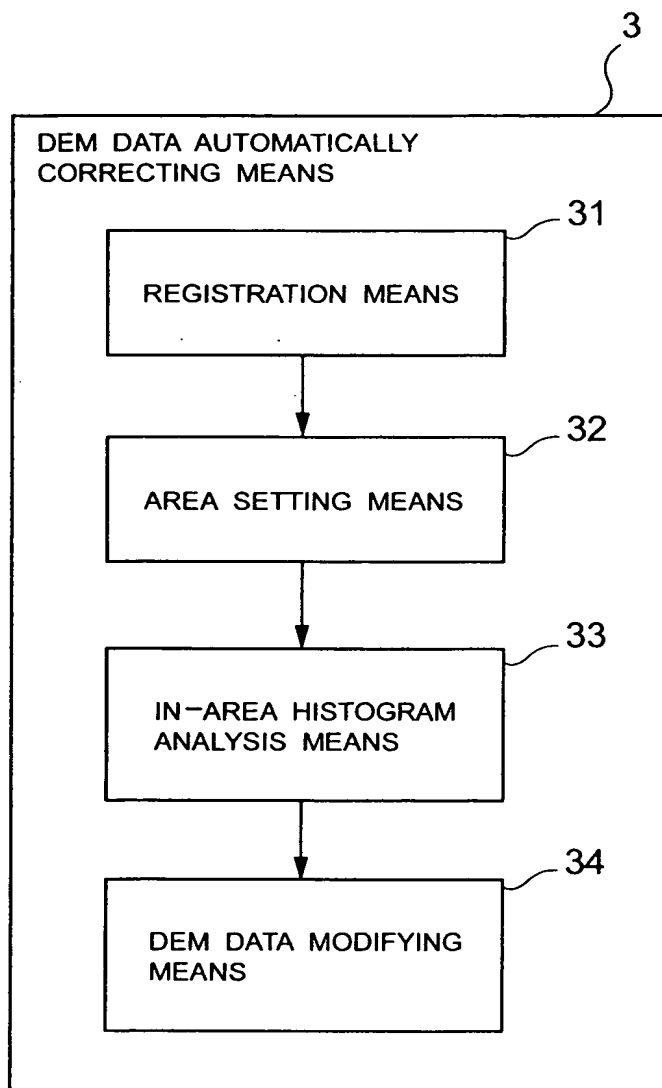


FIG. 1

2/46

FIG. 2



0996358-110801

```

graph TD
    START([START]) --> S1[PLURALITY OF IMAGES  
(STEREO IMAGES)  
FROM THE SAME POINT ON THE  
PHOTOGRAPHED FROM  
DIFFERENT VIEWPOINTS FROM  
THE POINT]
    S1 --> S2[SELECT SUBJECT SATELLITE  
IMAGES TO STEREO MATCHING  
AND TO GENERATE  
THREE-DIMENSIONAL DATA SHOWING  
FEATURES AROUND  
THE POINT]
    S2 --> S3[AUTOMATICALLY CORRECT ERRONEOUS  
THREE-DIMENSIONAL DATA BY  
ADDITIONAL DATA HAVING MAINLY  
INTERNAL SHAPE INFORMATION  
IN AN AREA CORRESPONDING TO  
THE THREE-DIMENSIONAL DATA, FOR THREE-  
DIMENSIONAL DATA OBTAINED BY  
STEREO MATCHING PROCESSING]
    S3 --> END([END])

```

FIG. 4

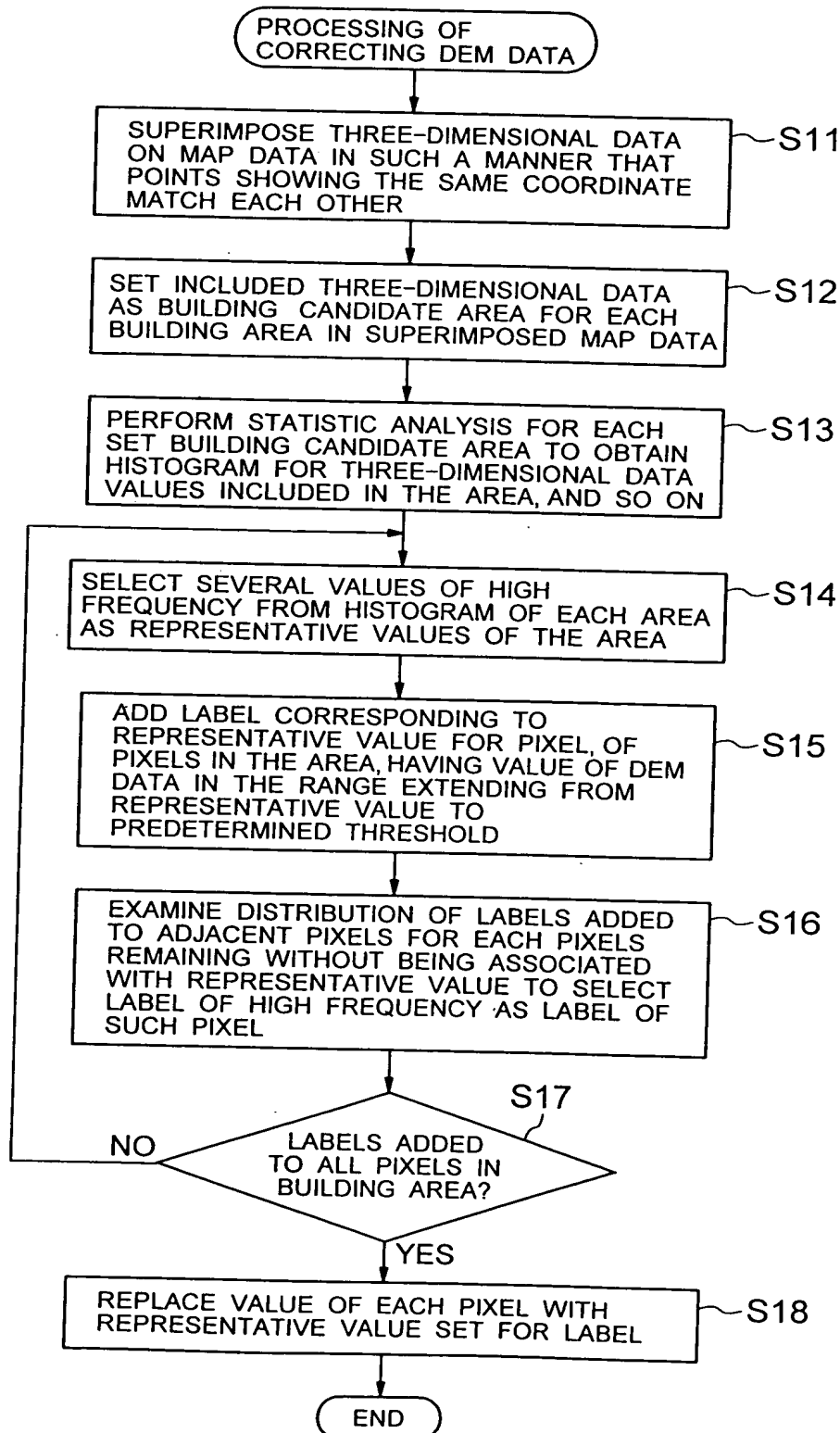
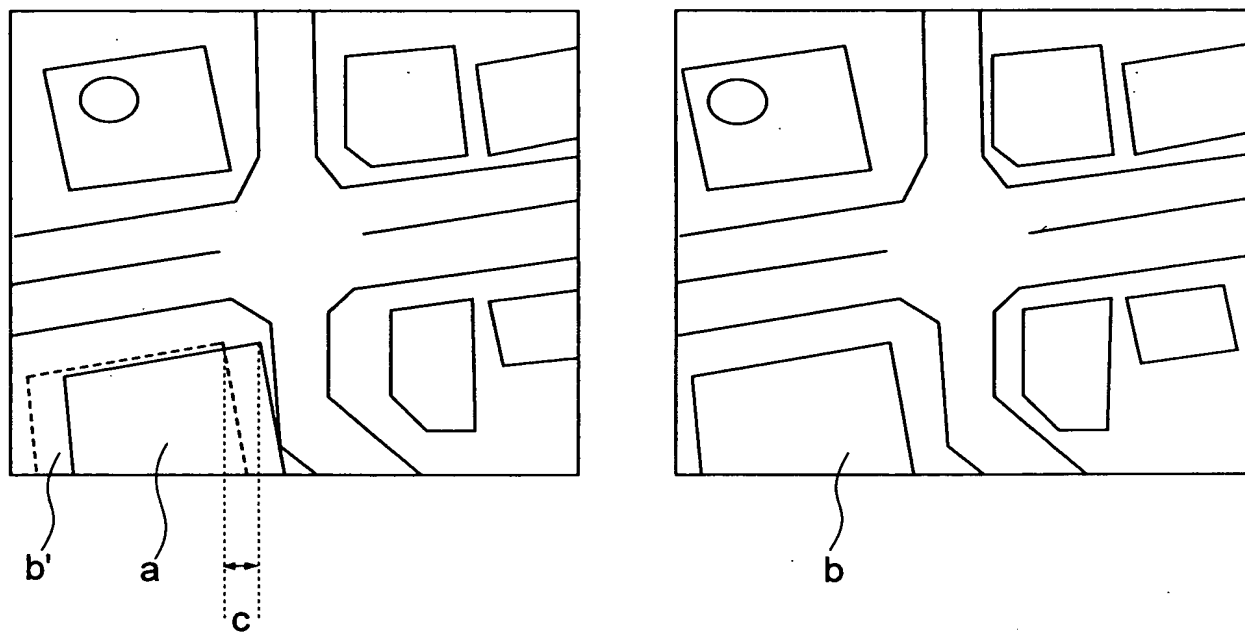


FIG.5



6/46

FIG.6A

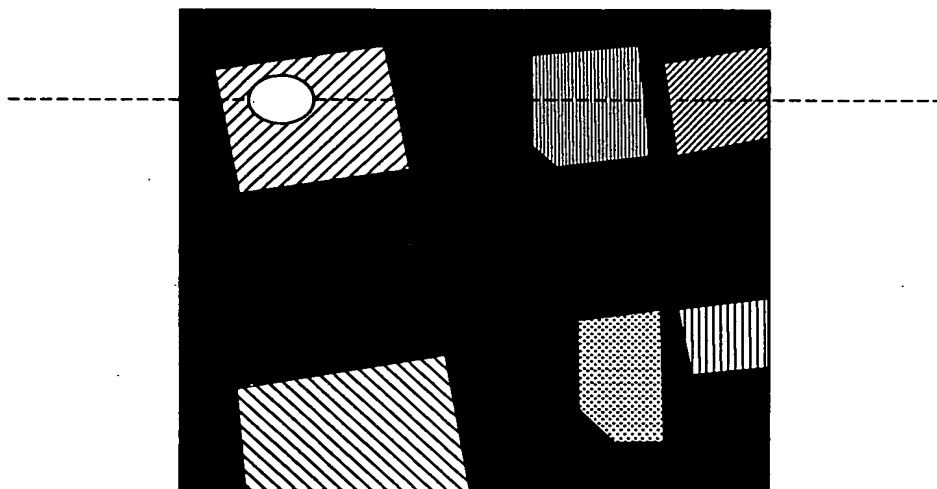
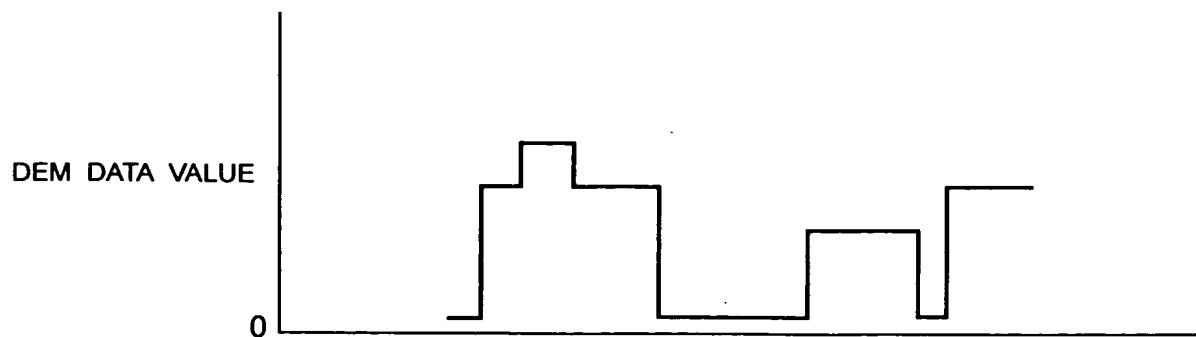


FIG.6B



7/46

FIG.7

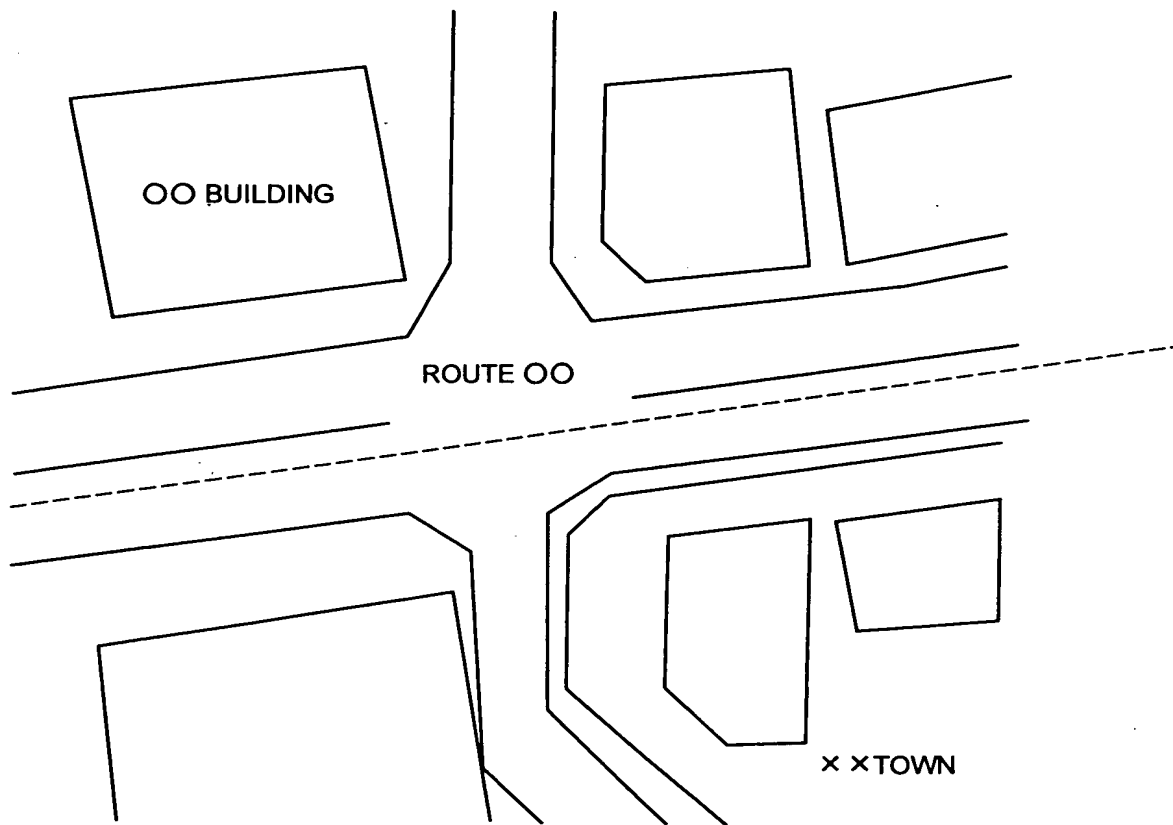


FIG. 7

FIG. 8A

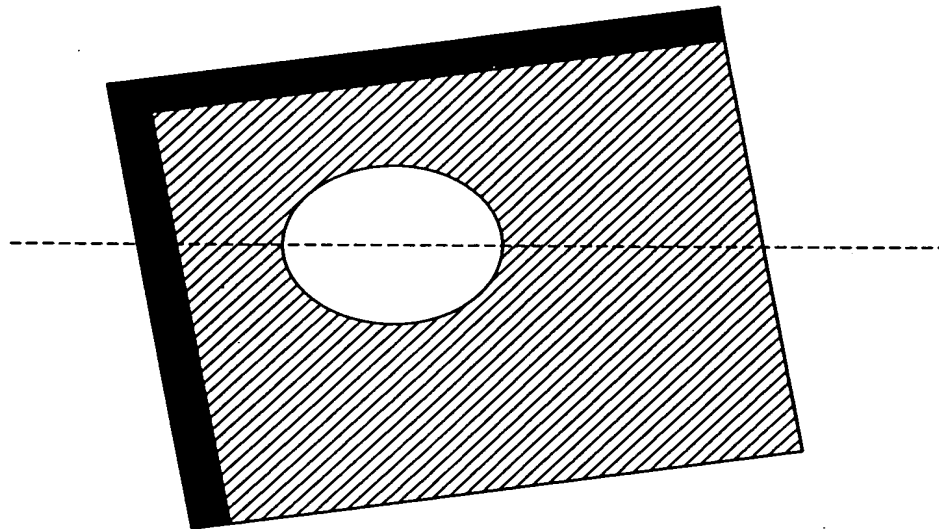
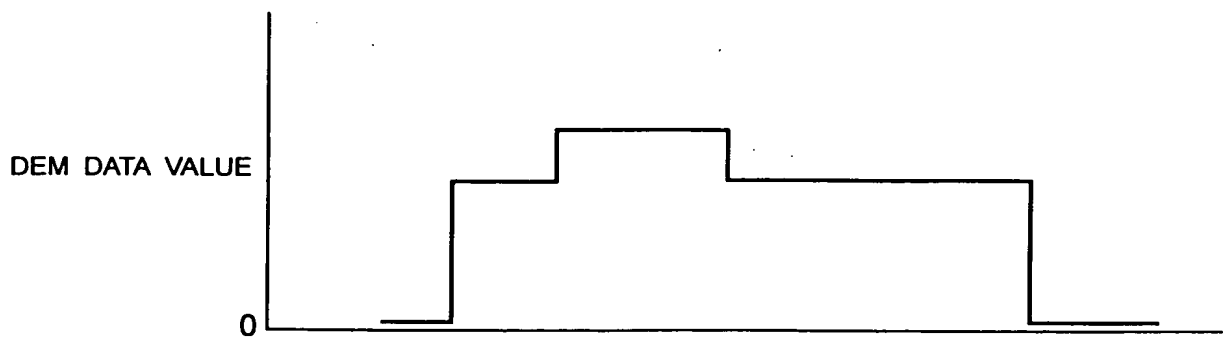
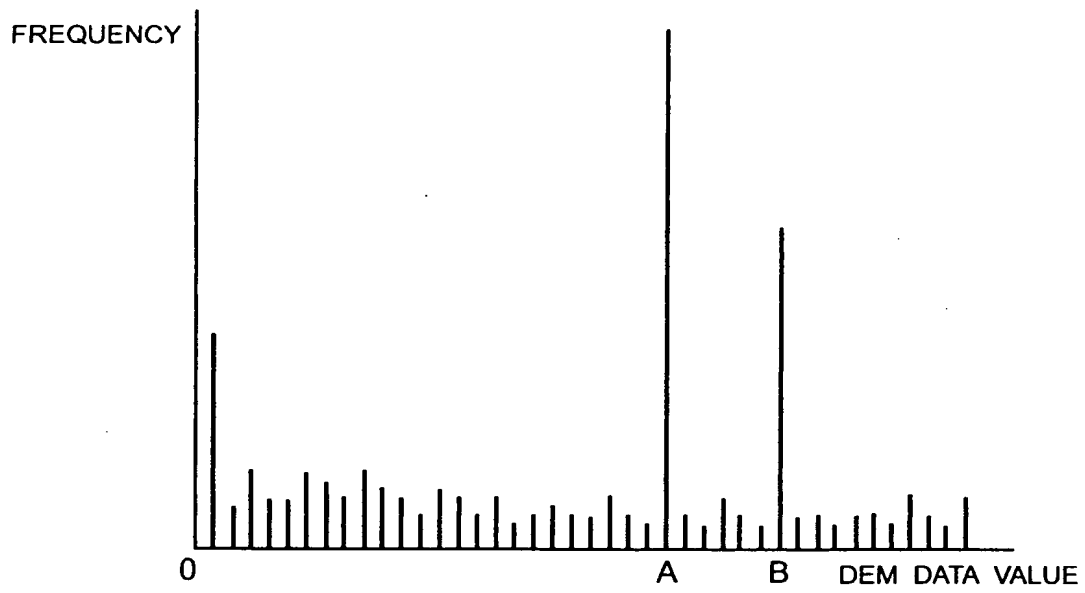


FIG. 8B



9/46

FIG.9



10/46

FIG.10A

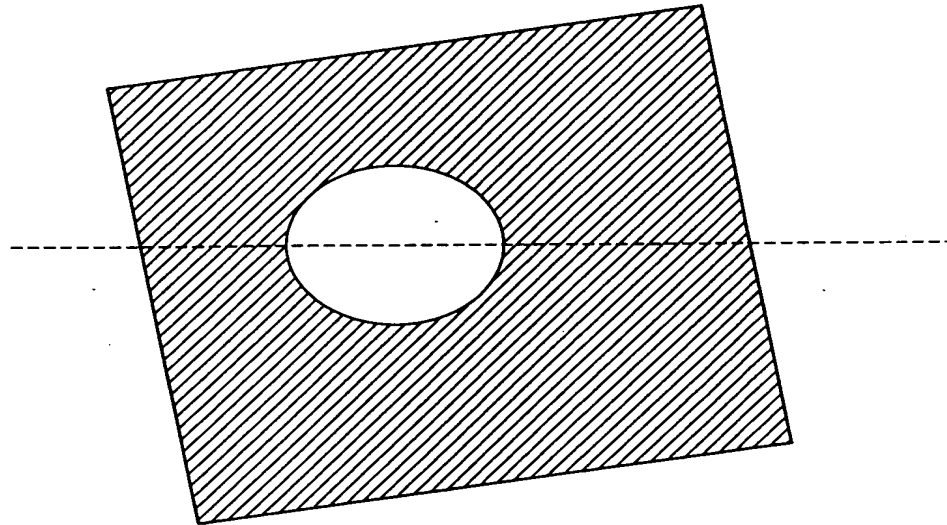


FIG.10B

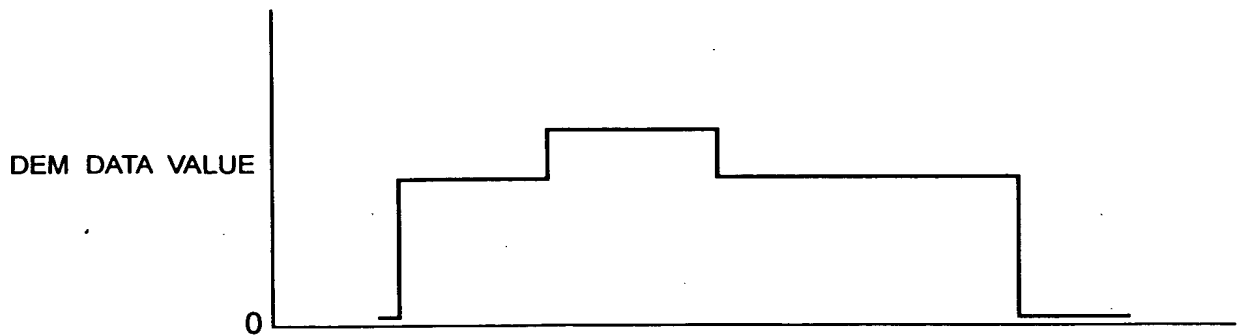


FIG. 11

1	1	1	1	1	1	4	4	5	5	5	5
1	1	1	4	4	4	4	5	5	5	5	5
1	4	4	4	5	5	5	5	5	5	6	6
4	4	5	5	5	5	6	8	8	6	8	8
4	5	5	5	5	5	6	8	6	7	8	8
5	5	5	5	5	5	5	6	7	8	8	8
5	5	5	5	5	5	6	7	8	8	8	8
5	5	5	5	5	5	6	8	8	8	8	8

FIG. 11

FOOT" 35E98660

12/46

Title: STEREO IMAGE PROCESSING
STATUS AND METHOD OF PROCESSING
STEREO IMAGE
Inventor(s): Hisao FURUKAWA
Docket No. 053969-0132

FIG. 12

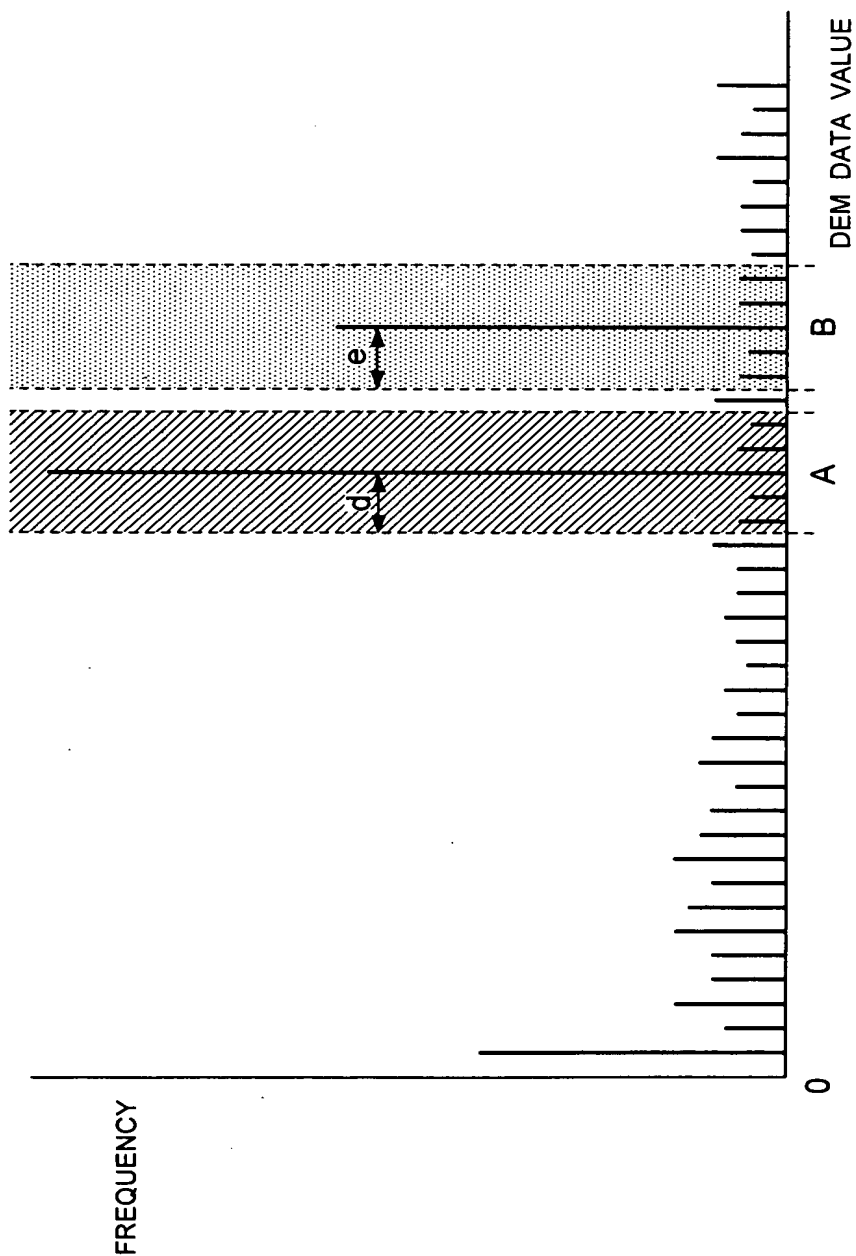


FIG. 13

1	1	1	1	1	1	A	A	A	A	A	A
1	1	1	A	A	A	A	A	A	A	A	A
1	A	A	A	A	A	A	A	A	A	A	A
A	A	A	A	A	A	A	A	A	A	B	B
A	A	A	A	A	A	A	A	A	B	B	B
A	A	A	A	A	A	A	A	B	B	B	B
A	A	A	A	A	A	A	B	B	B	B	B
A	A	A	A	A	A	A	B	B	B	B	B

FIG. 13

14/46

FIG. 14

9

f

1	1	1	1	1	1	A	A	A	A	A	A
1	1	1	A	A	A	A	A	A	A	A	A
1	A	A	A	A	A	A	A	A	A	A	A
A	A	A	A	A	A	A	A	A	A	B	B
A	A	A	A	A	A	A	A	A	B	B	B
A	A	A	A	A	A	A	A	B	B	B	B
A	A	A	A	A	A	A	B	B	B	B	B
A	A	A	A	A	A	A	B	B	B	B	B

FIG. 14

FIG. 15

A	A	A	A	A	A	A	A	A	A	A	A
A	A	A	A	A	A	A	A	A	A	A	A
A	A	A	A	A	A	A	A	A	A	A	A
A	A	A	A	A	A	A	A	A	A	B	B
A	A	A	A	A	A	A	A	A	B	B	B
A	A	A	A	A	A	A	A	B	B	B	B
A	A	A	A	A	A	A	B	B	B	B	B
A	A	A	A	A	A	A	B	B	B	B	B

FIG. 15 is a diagram illustrating a stereo image processing apparatus and method of processing a stereo image.

FIG. 16

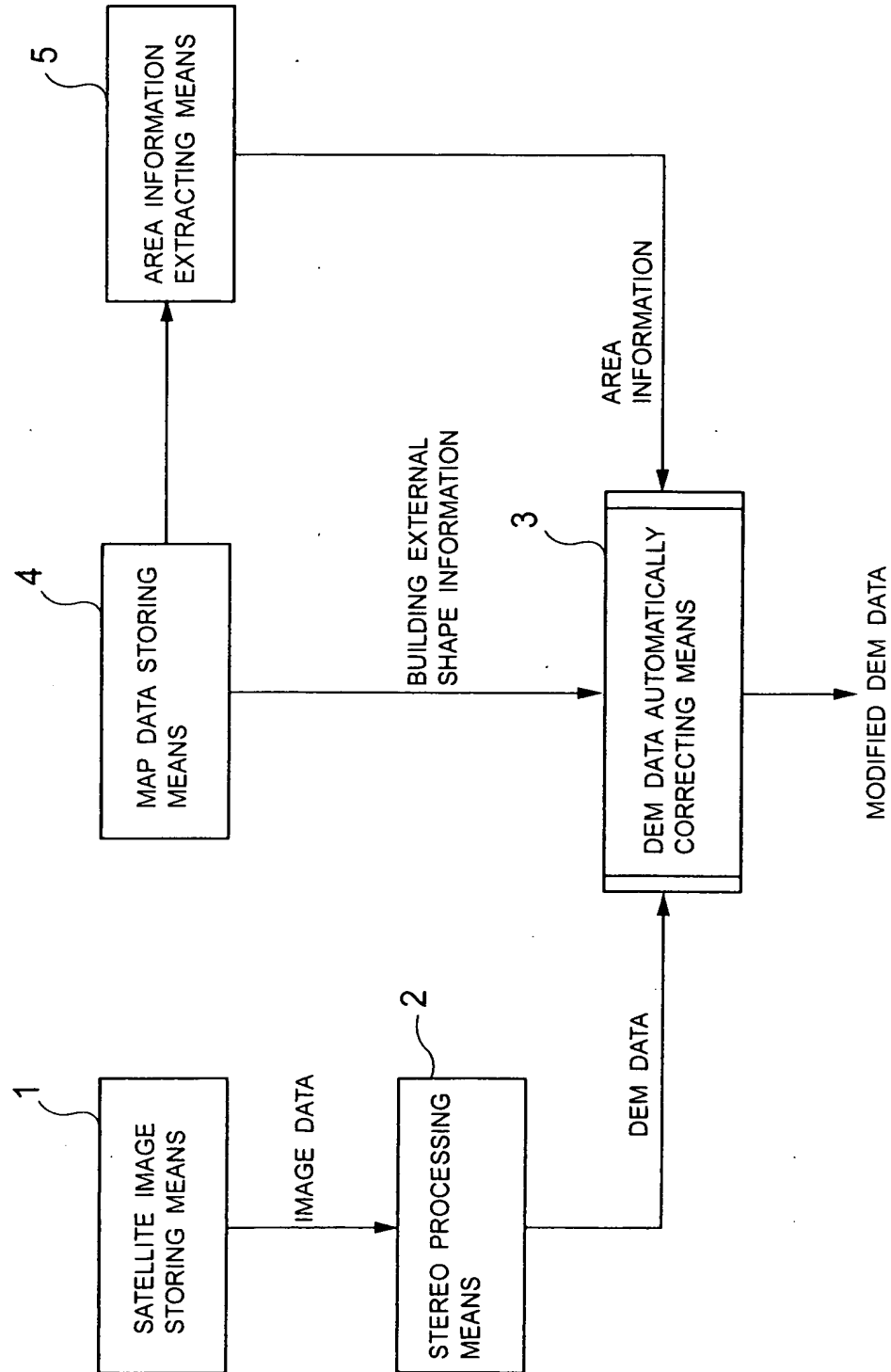


FIG. 17

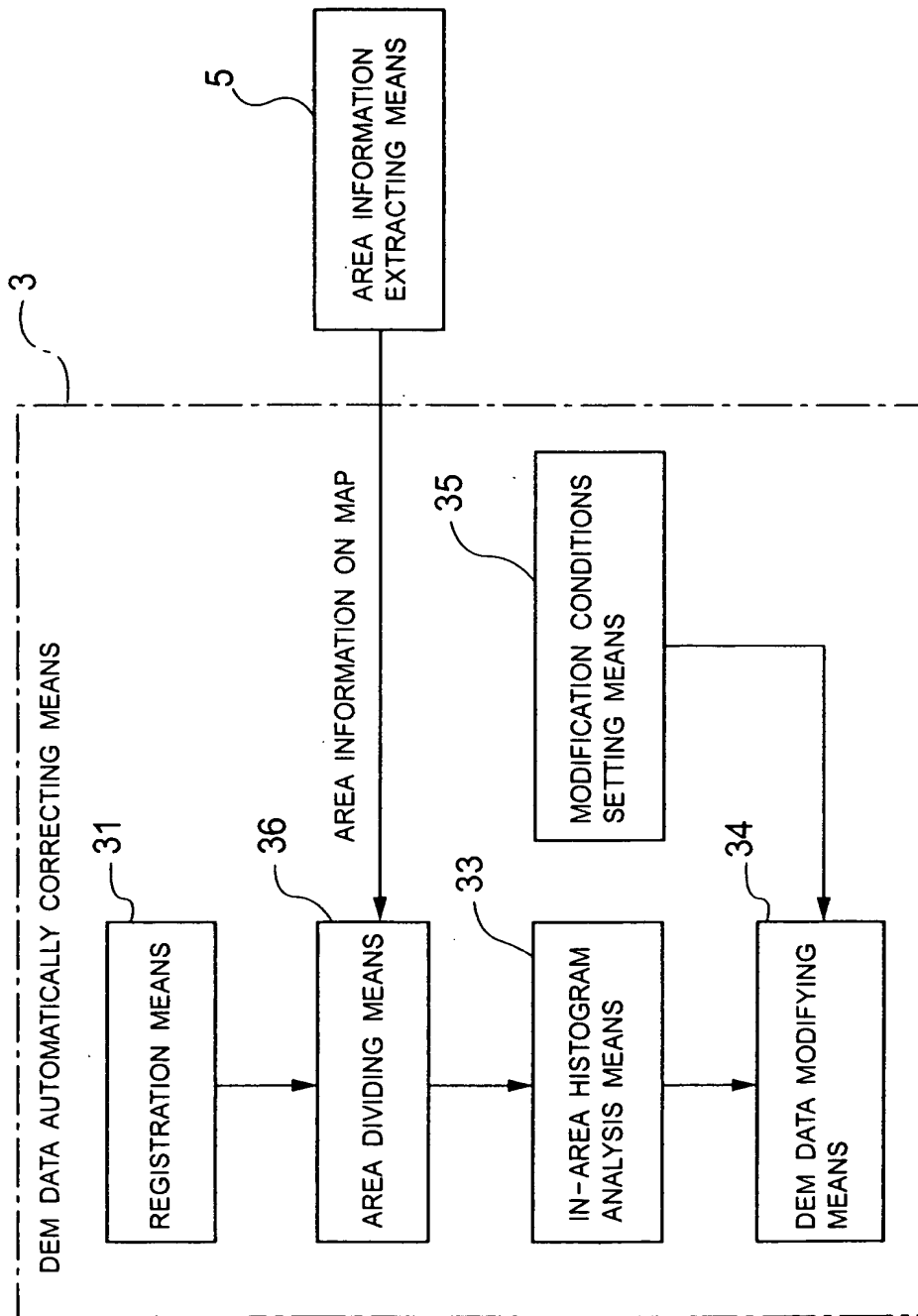
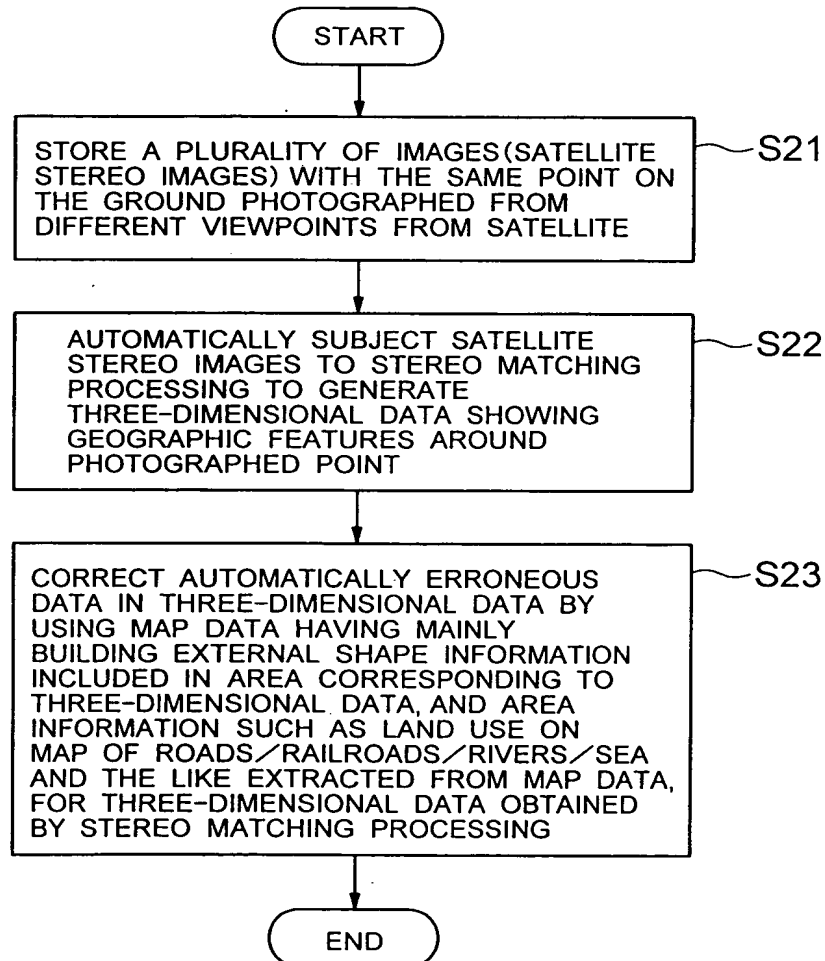


FIG. 18



19/46

FIG. 19A

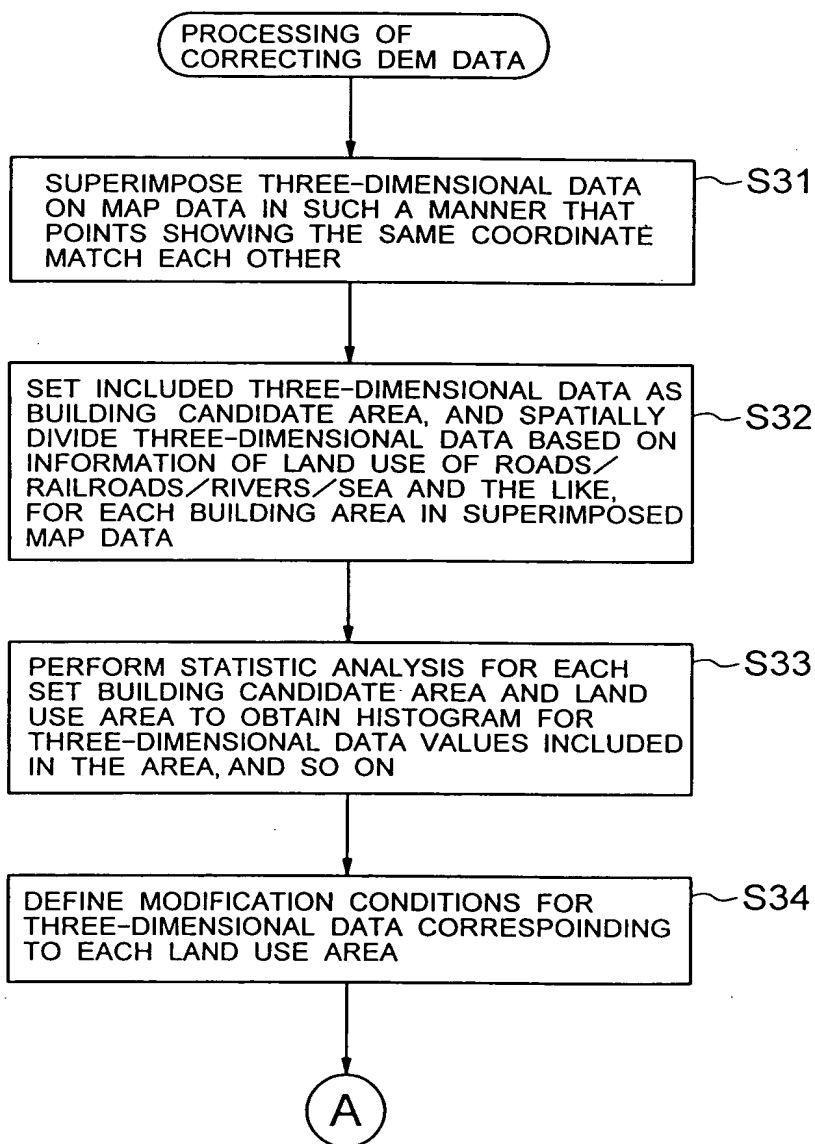
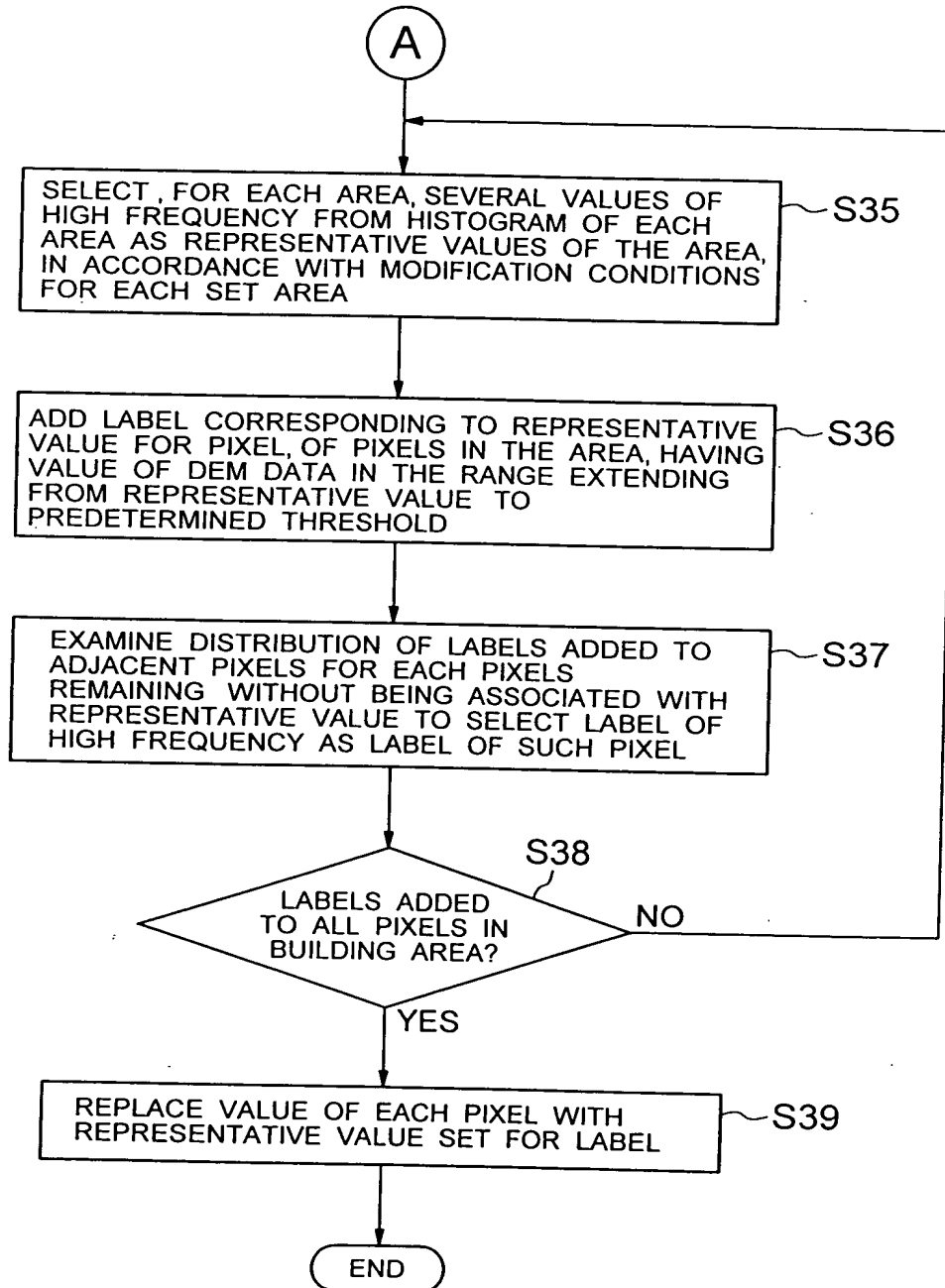


FIG. 19A

20/46

FIG. 19B



09986358 110801

21/46

FIG.20

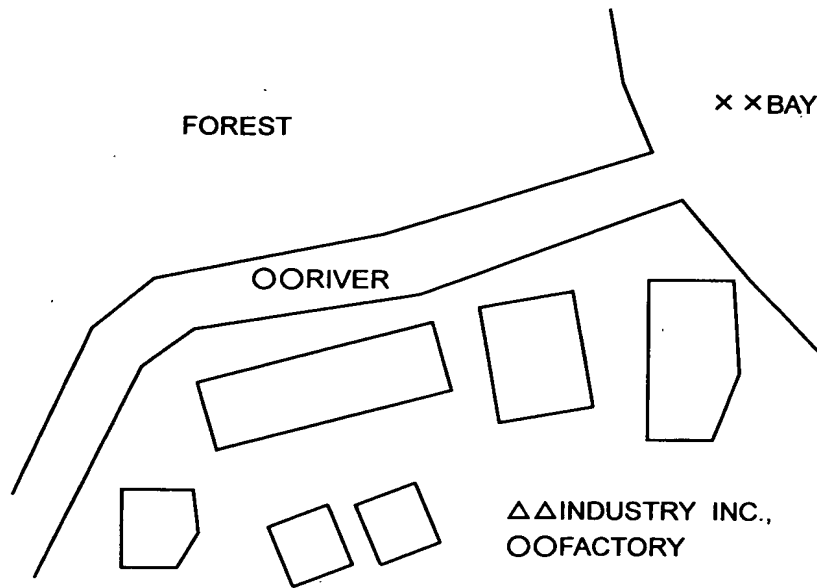


FIG. 20

22/46

FIG. 21

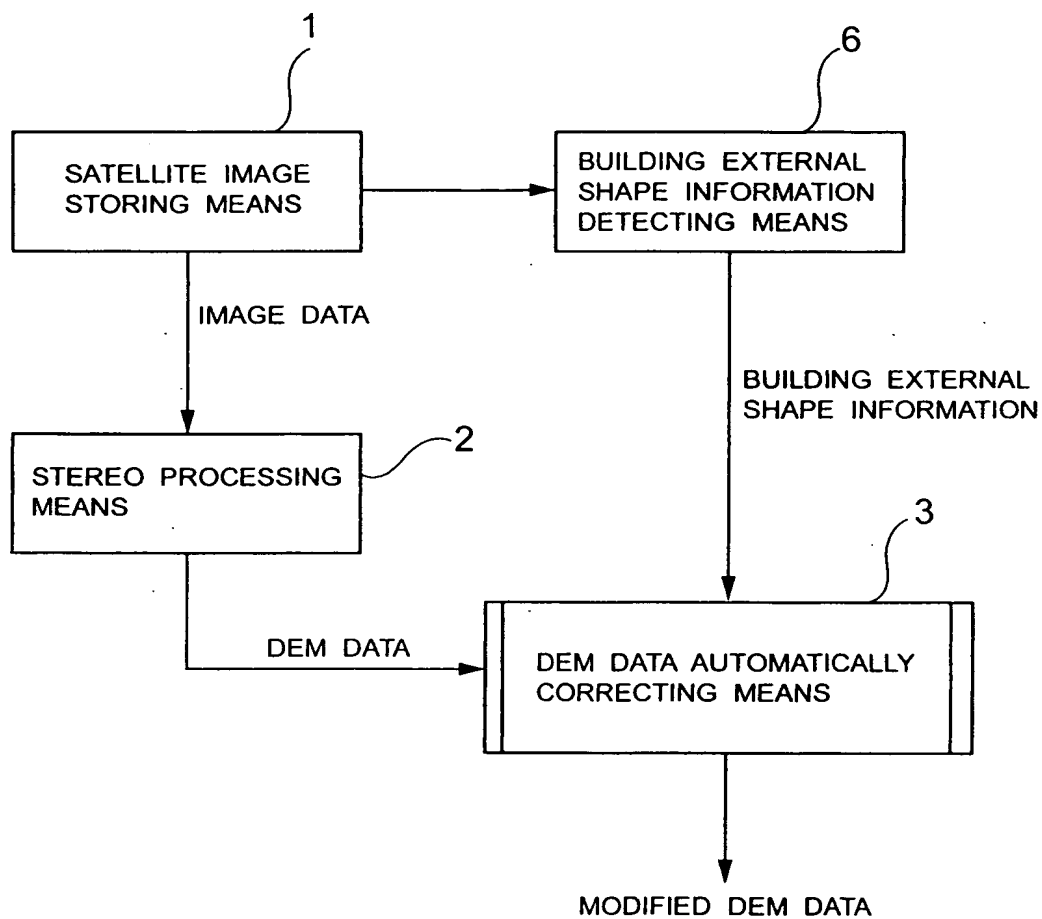
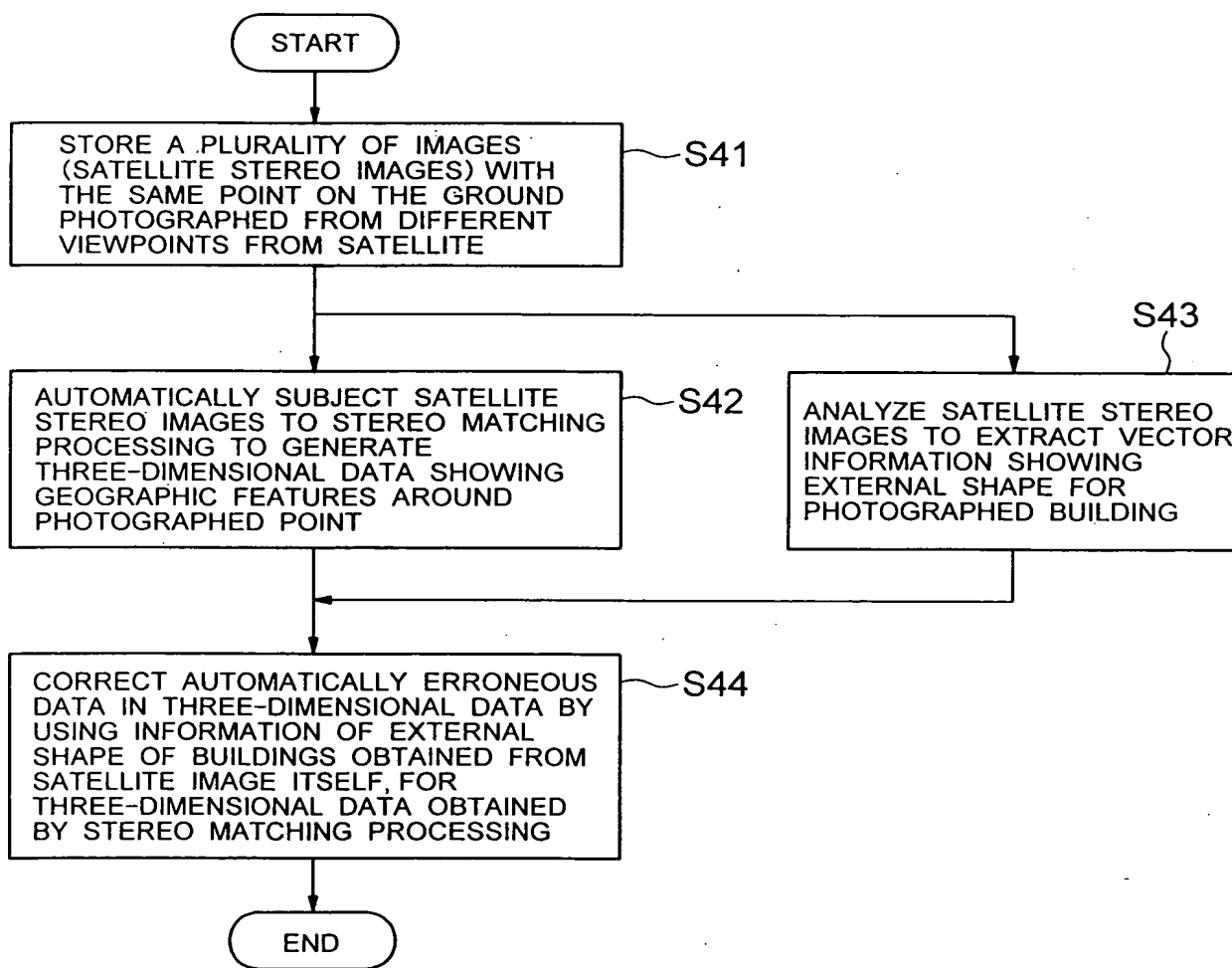


FIG. 21

23/46

FIG. 22

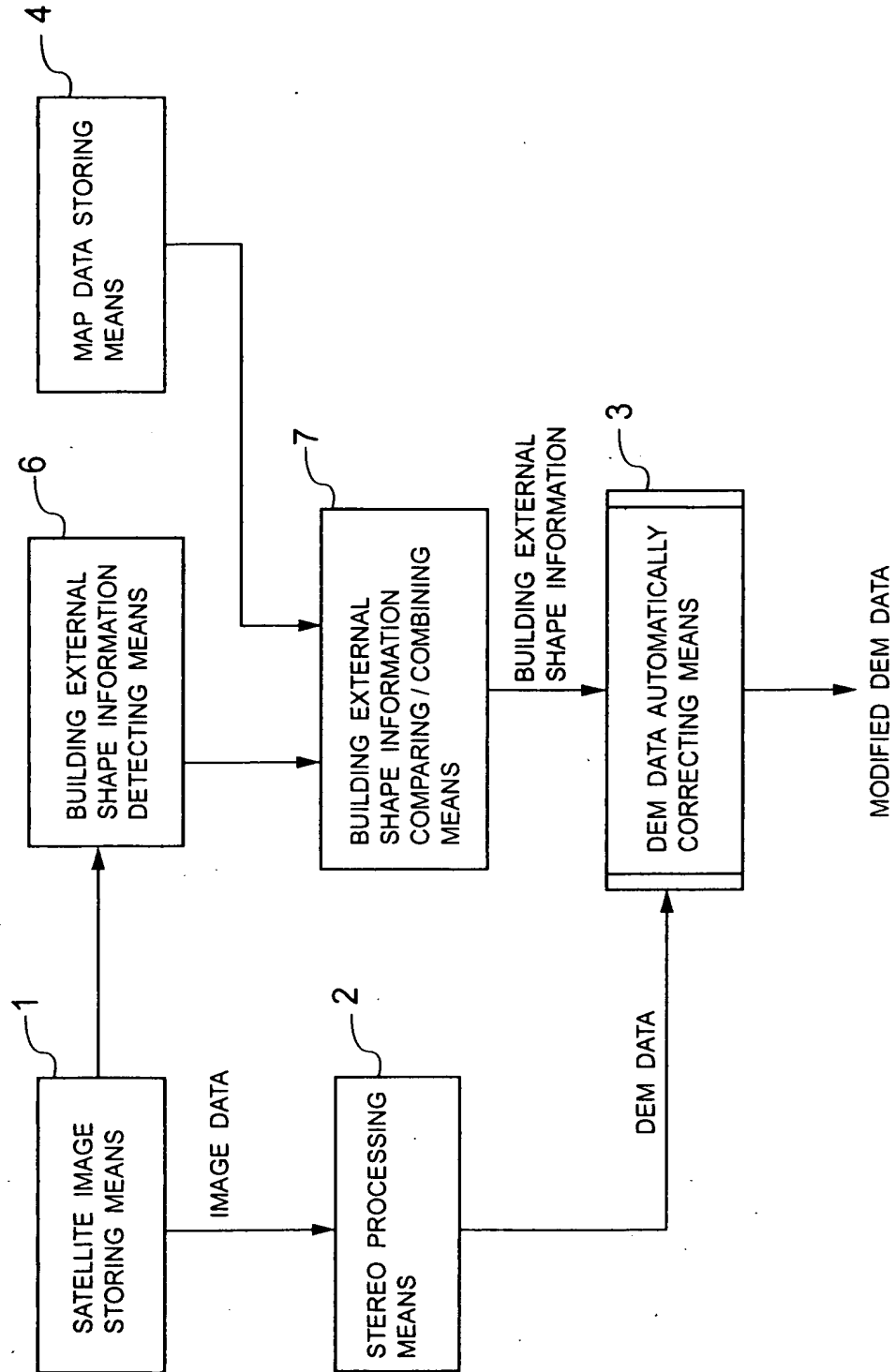


PROCESSING OF
CORRECTING DEM DATA



25/46

FIG. 24



26/46

FIG. 25

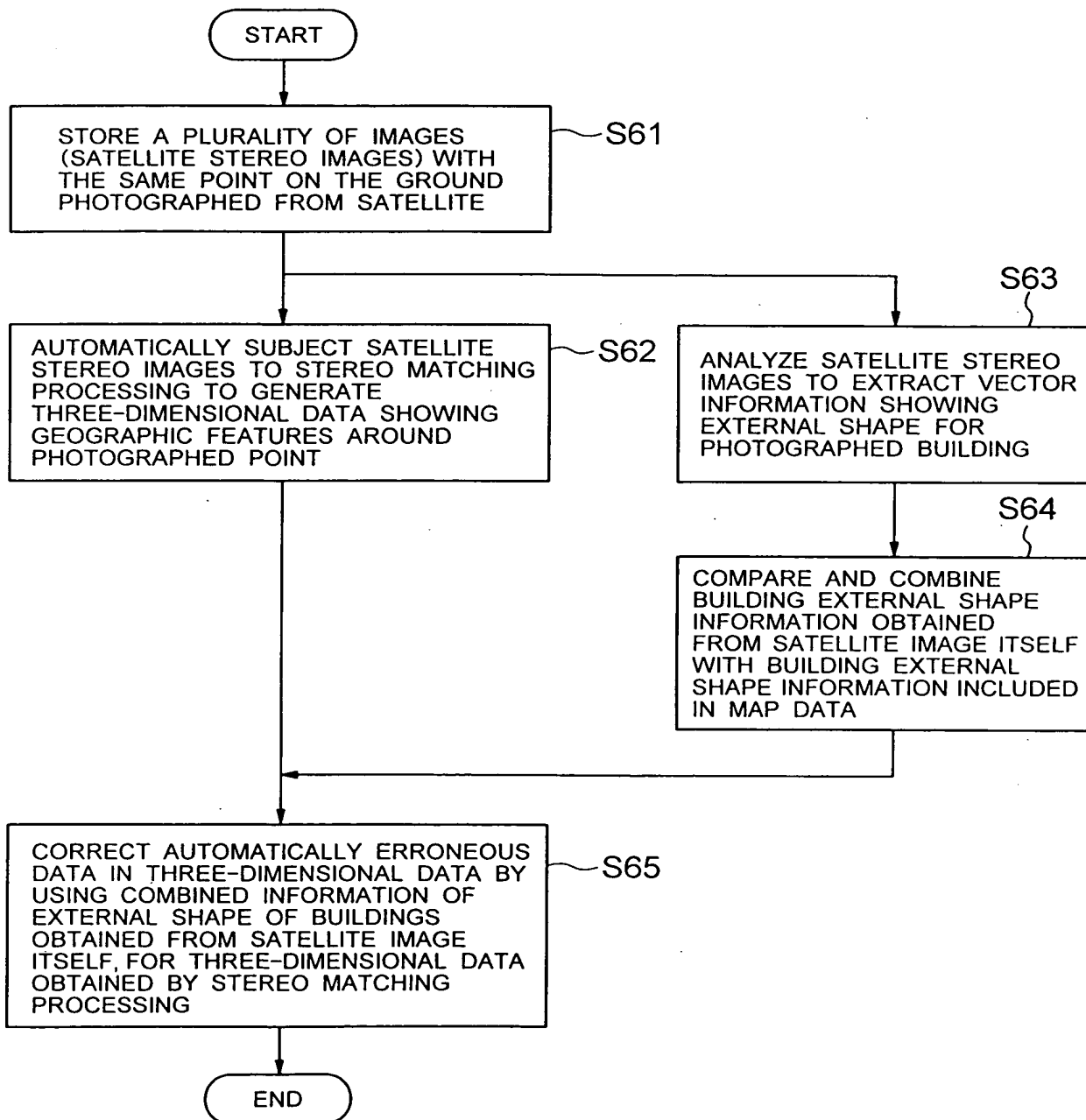
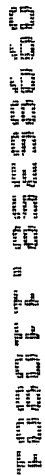
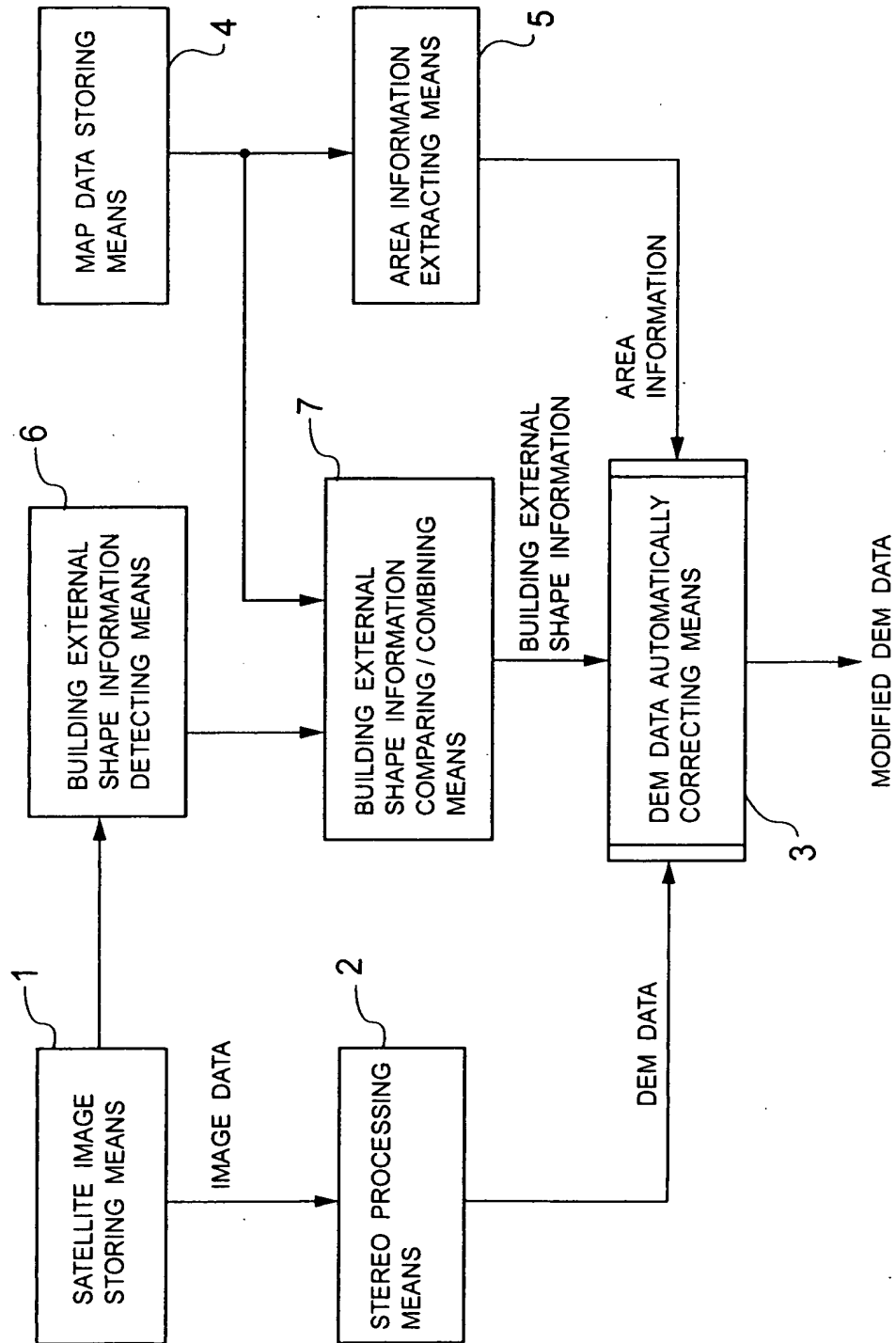


FIG. 25



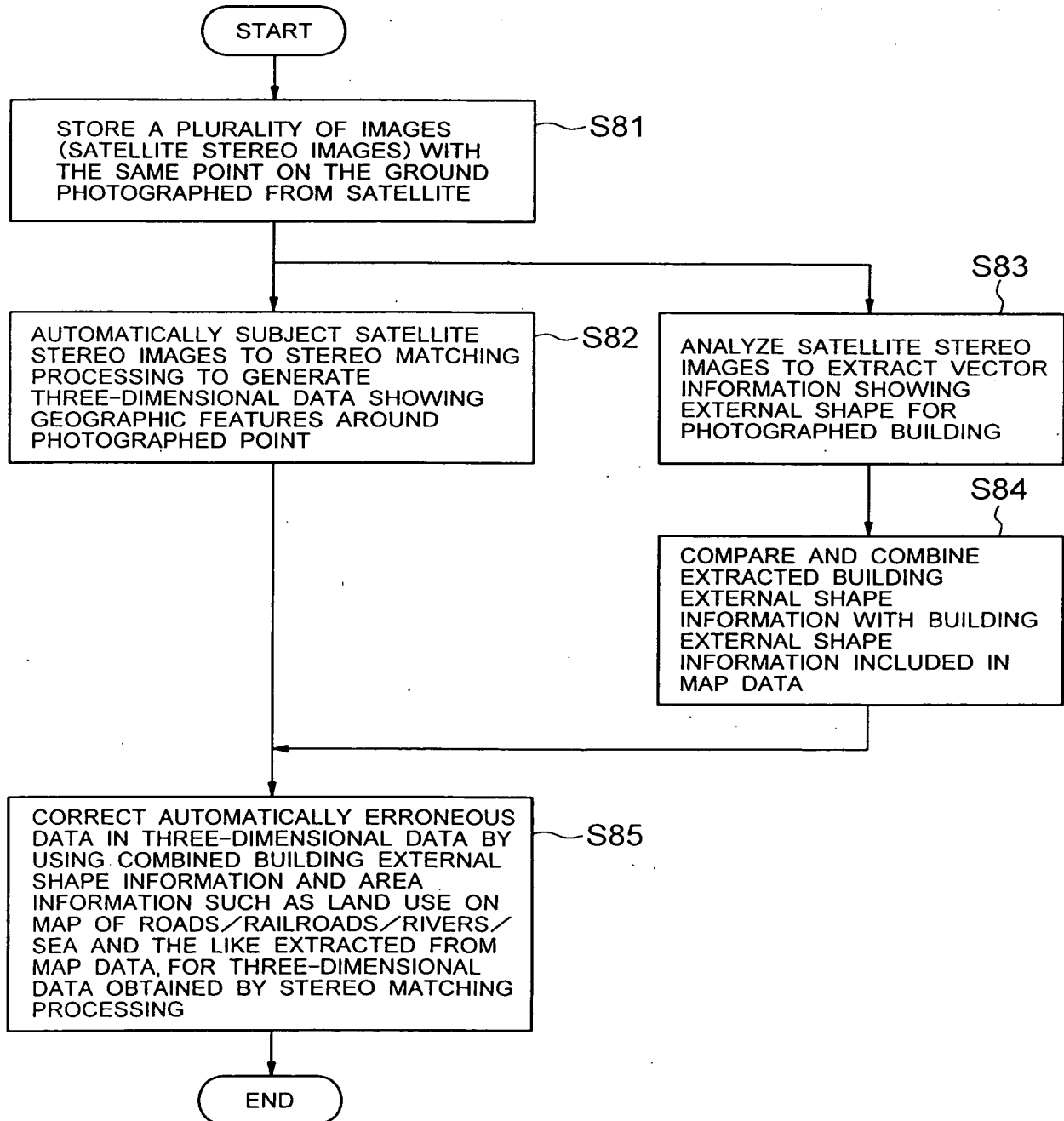
28/46

FIG. 27



29/46

FIG. 28



30/46

FIG. 29A

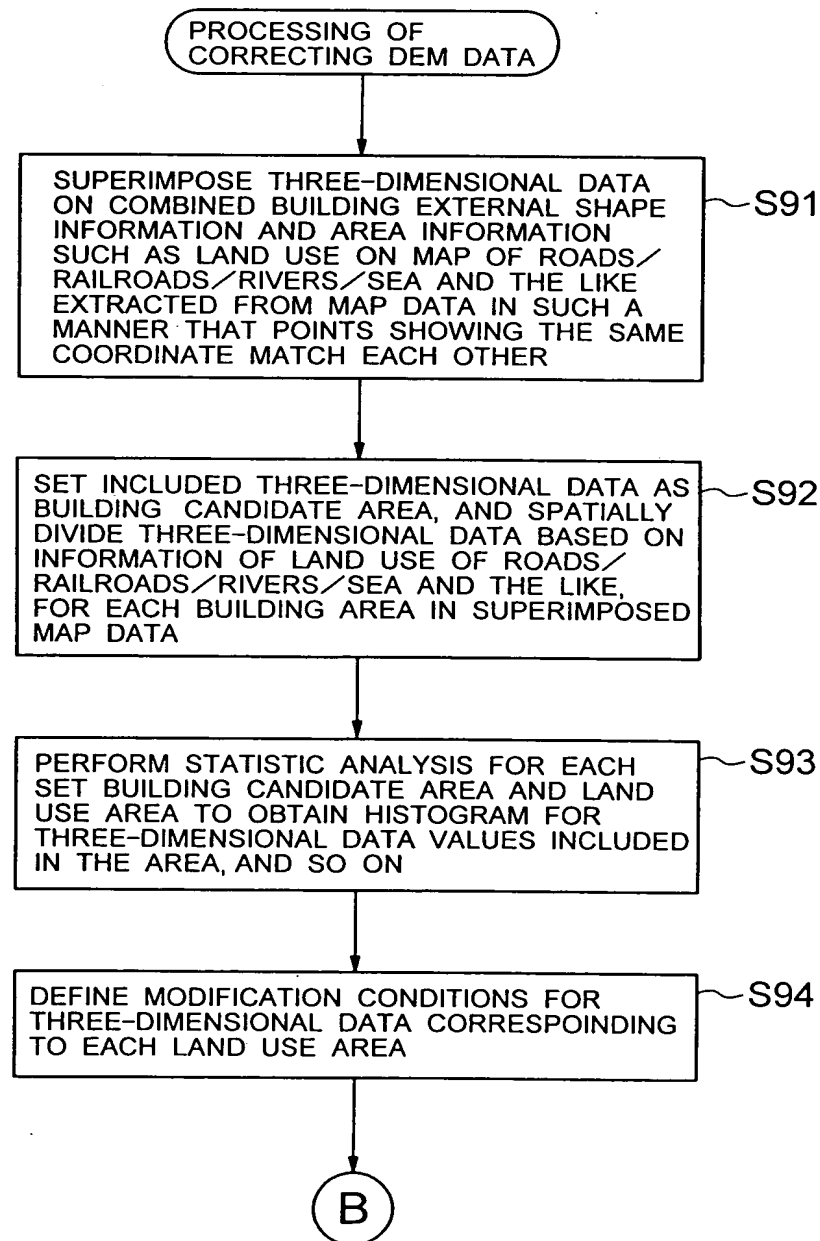


FIG. 29A

31/46

FIG. 29B

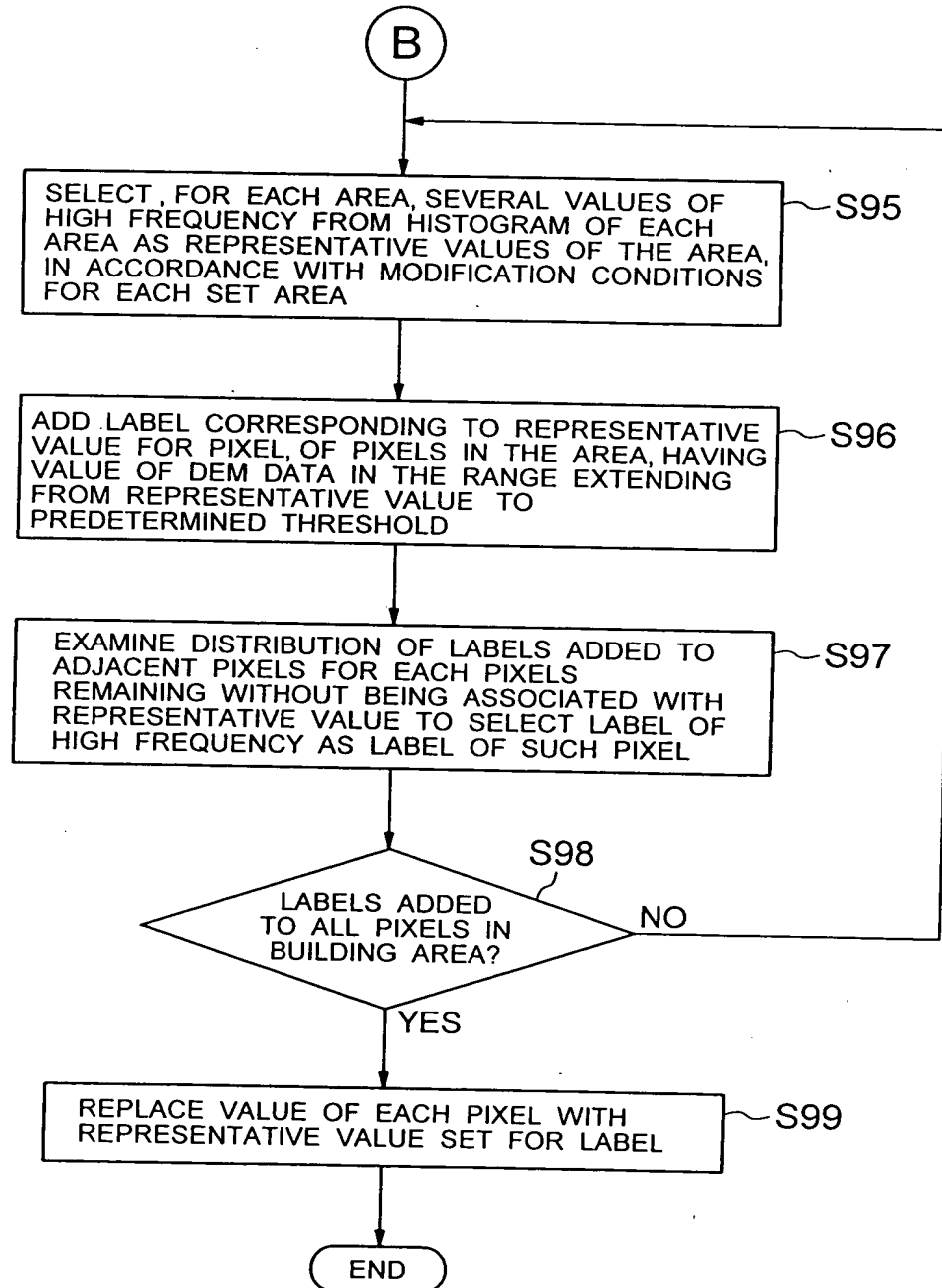


FIG. 29B

32/46

FIG. 30

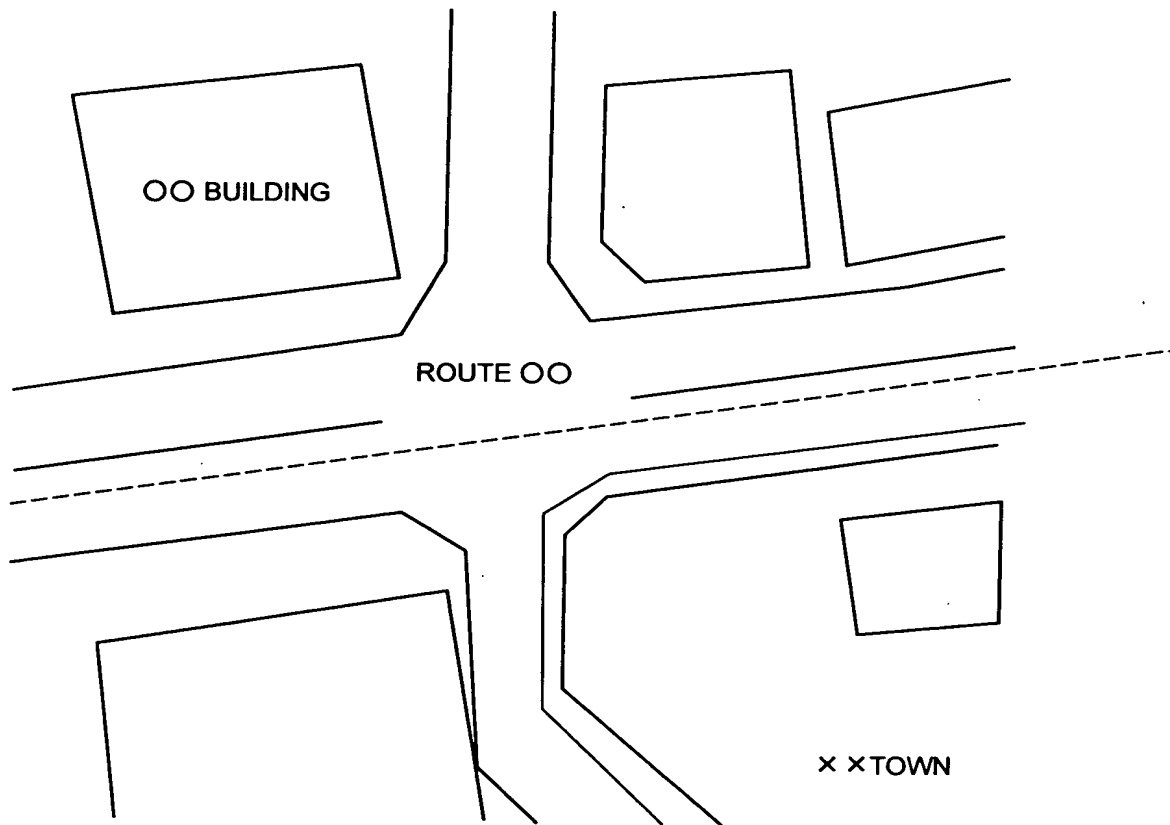


FIG. 30


```
graph TD
    1[SATELLITE IMAGE STORING MEANS] --> 6[BUILDING EXTERNAL SHAPE INFORMATION DETECTING MEANS]
    1 --> 2[STEREO PROCESSING MEANS]
    2 --> 3[DEM DATA AUTOMATICALLY CORRECTING MEANS]
    2 --> 4[MAP DATA STORING MEANS]
    4 --> 6
    4 --> 10[MAP DATA MODIFYING MEANS]
    6 --> 7[BUILDING EXTERNAL SHAPE INFORMATION COMPARING / COMBINING MEANS]
    7 --> 3
    3 --> 8[DEM DATA STORING MEANS]
    3 --> 9[DEM DATA COMPARING MEANS]
    8 --> 9
    9 --> 10
    10 --> 3
    9 --> 11[DIFFERENTIAL INFORMATION]
```

The diagram illustrates a system for correcting DEM data using building shape information. The process begins with satellite image data being stored (1) and then processed (2) to generate DEM data. This DEM data is then compared (9) with past DEM data (8) to identify differential information. This information is used to modify map data (10), which is then used to detect building external shape information (6). This information is compared and combined (7) with the original DEM data to produce corrected DEM data (3), which is then stored (8).

34/46

FIG. 32

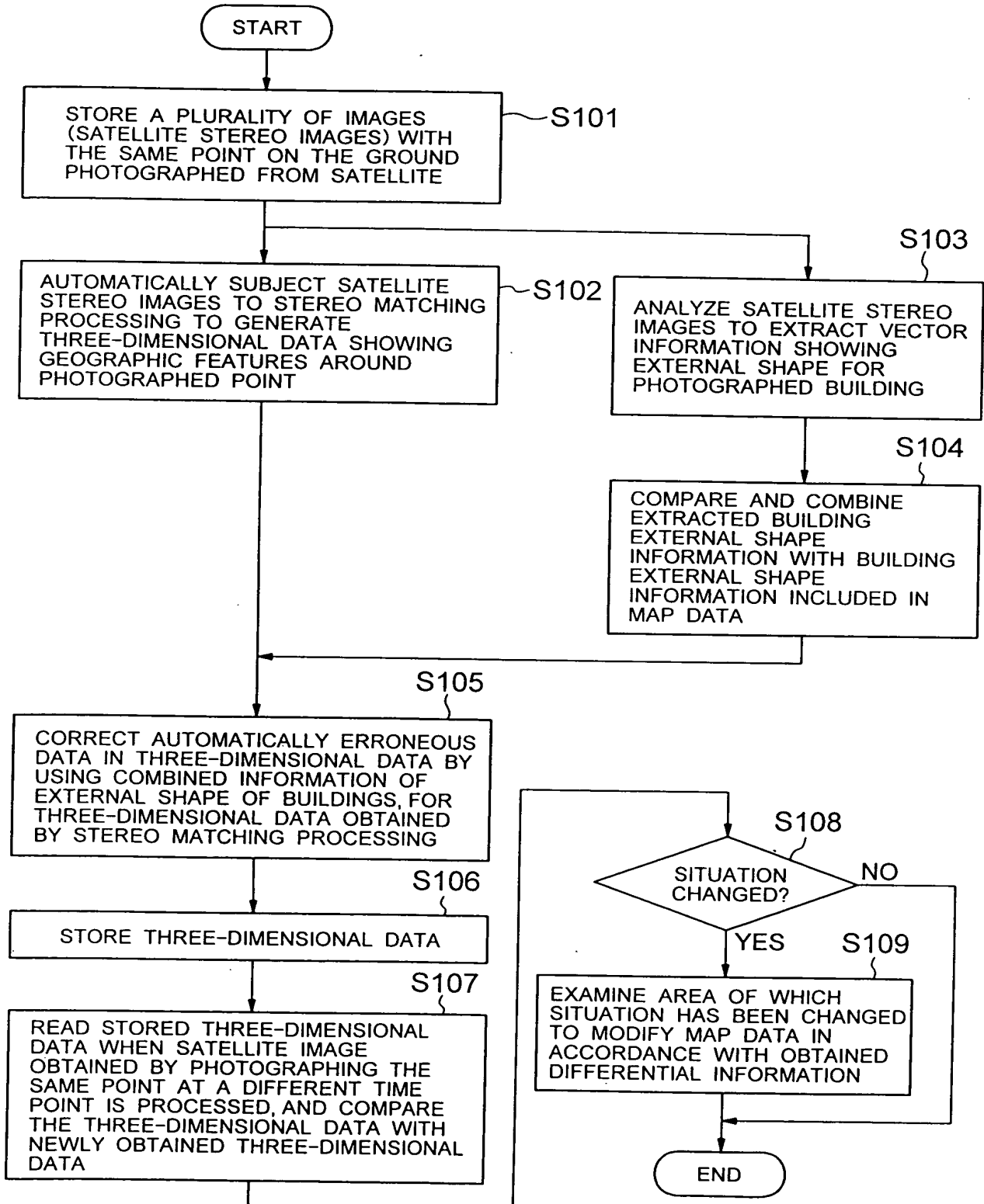


FIG. 32

35/46

FIG. 33

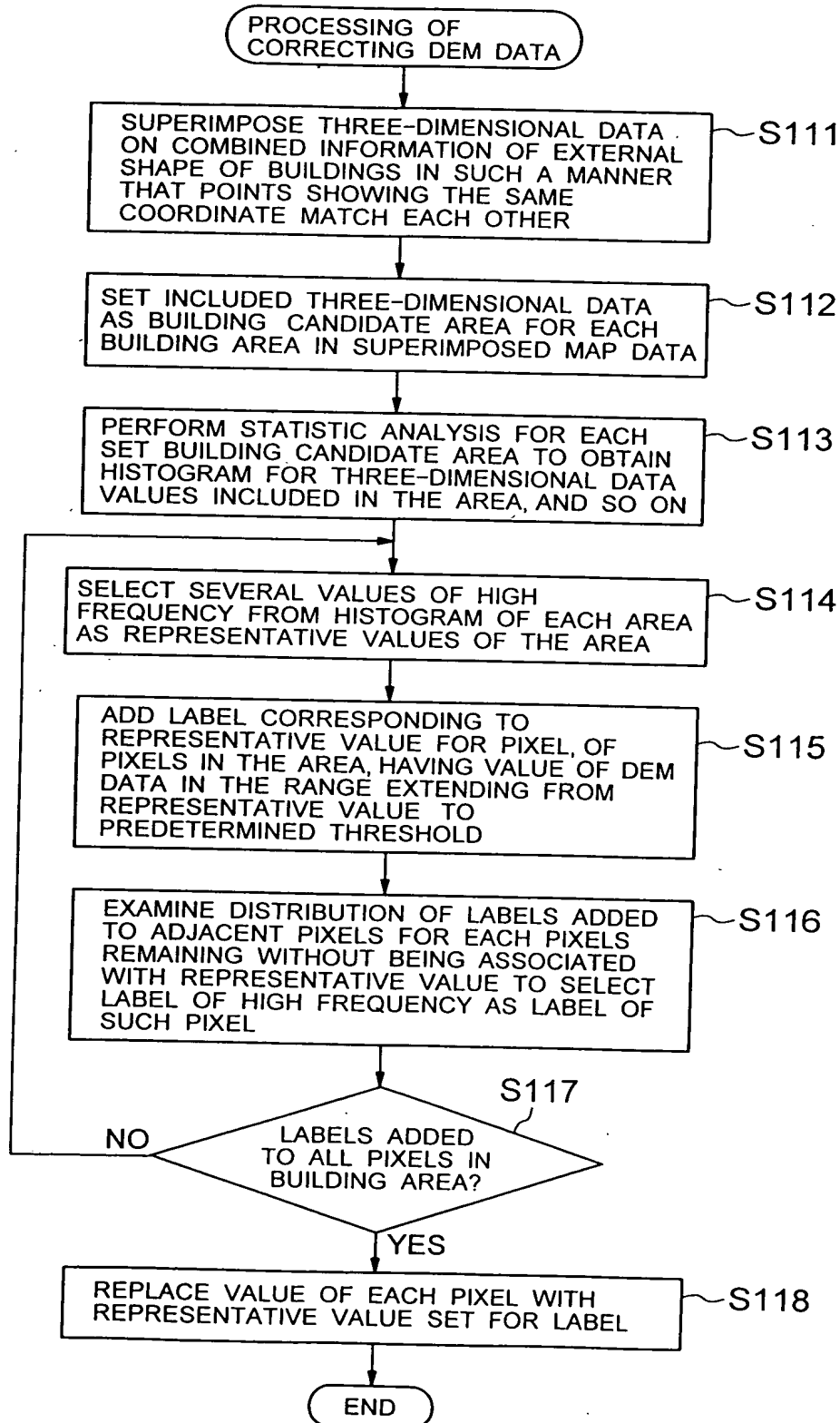


FIG. 33

36/46

FIG.34

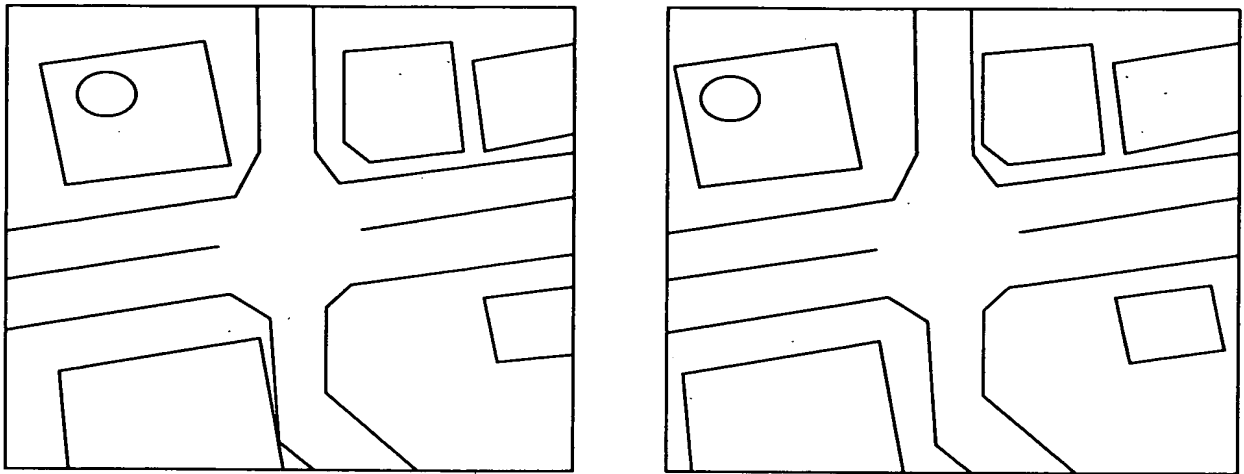
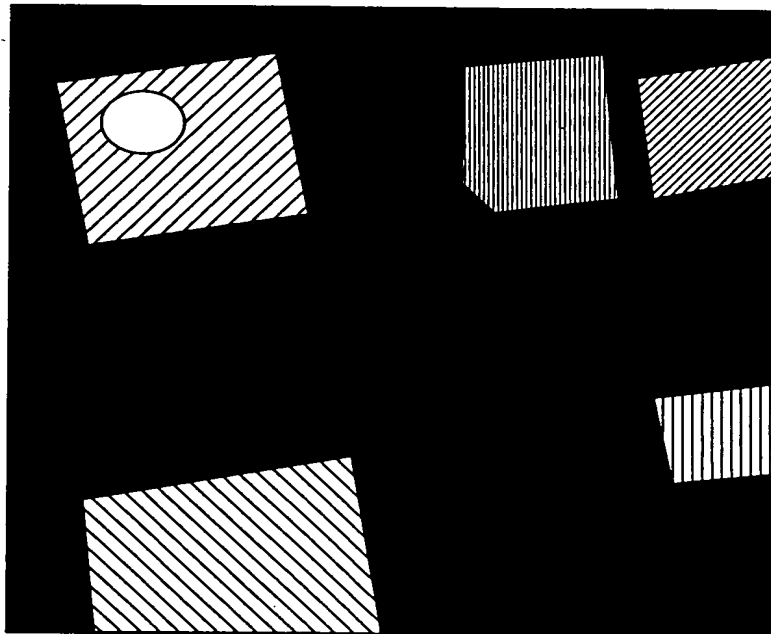


FIG. 34

37/46

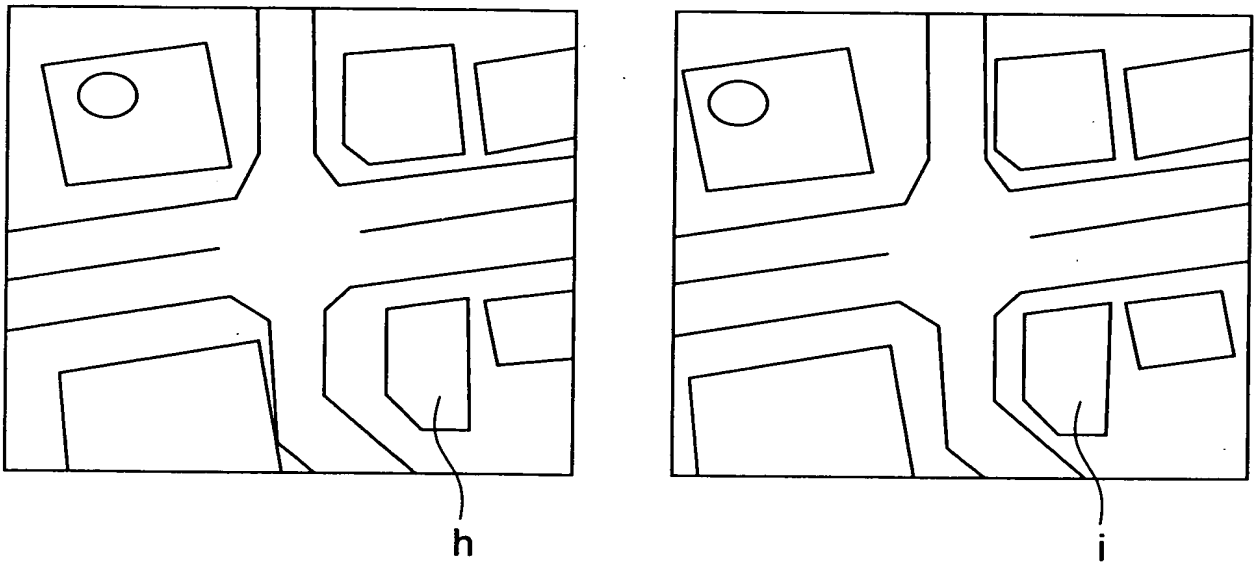
FIG. 35



1. The first step is to identify the problem or question that needs to be addressed. This involves understanding the context and the specific requirements of the task.

38/46

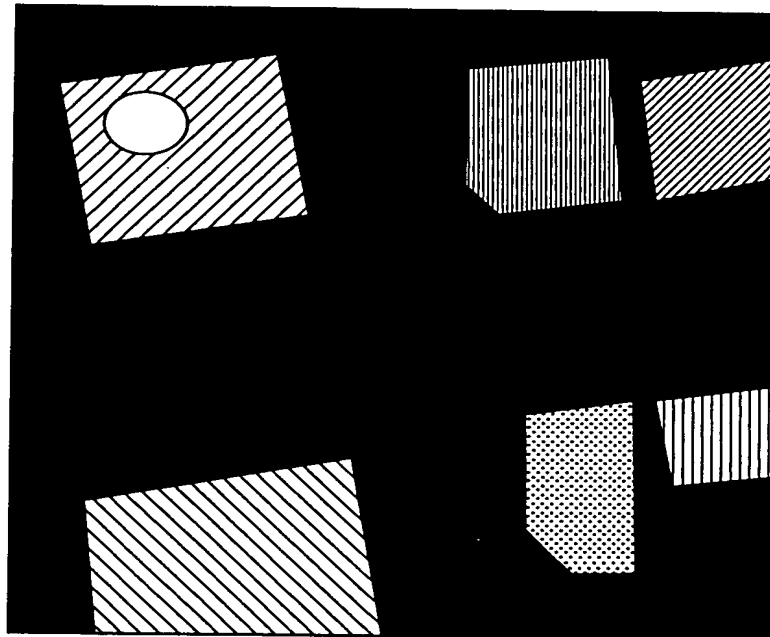
FIG.36



0996666-10001

39/46

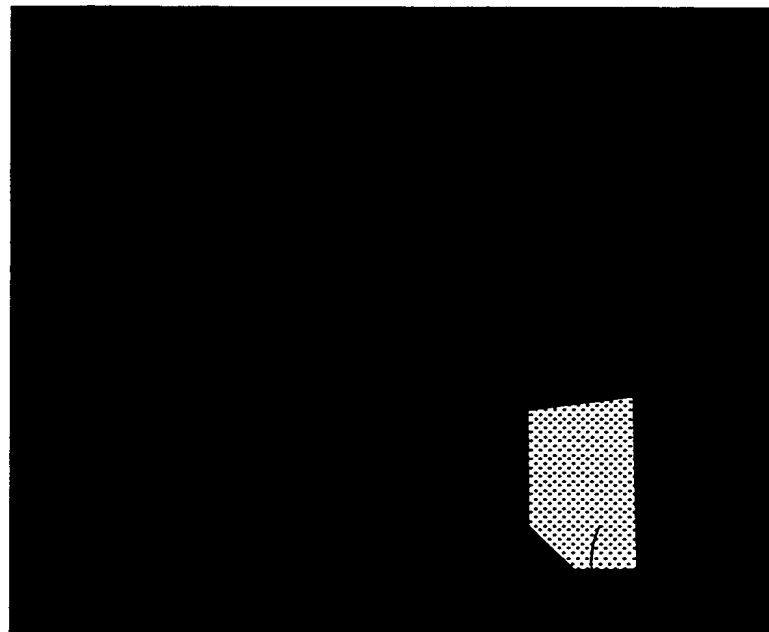
FIG.37



09086250 40001

40/46

FIG.38



h

0908350-110804

41/46

FIG.39

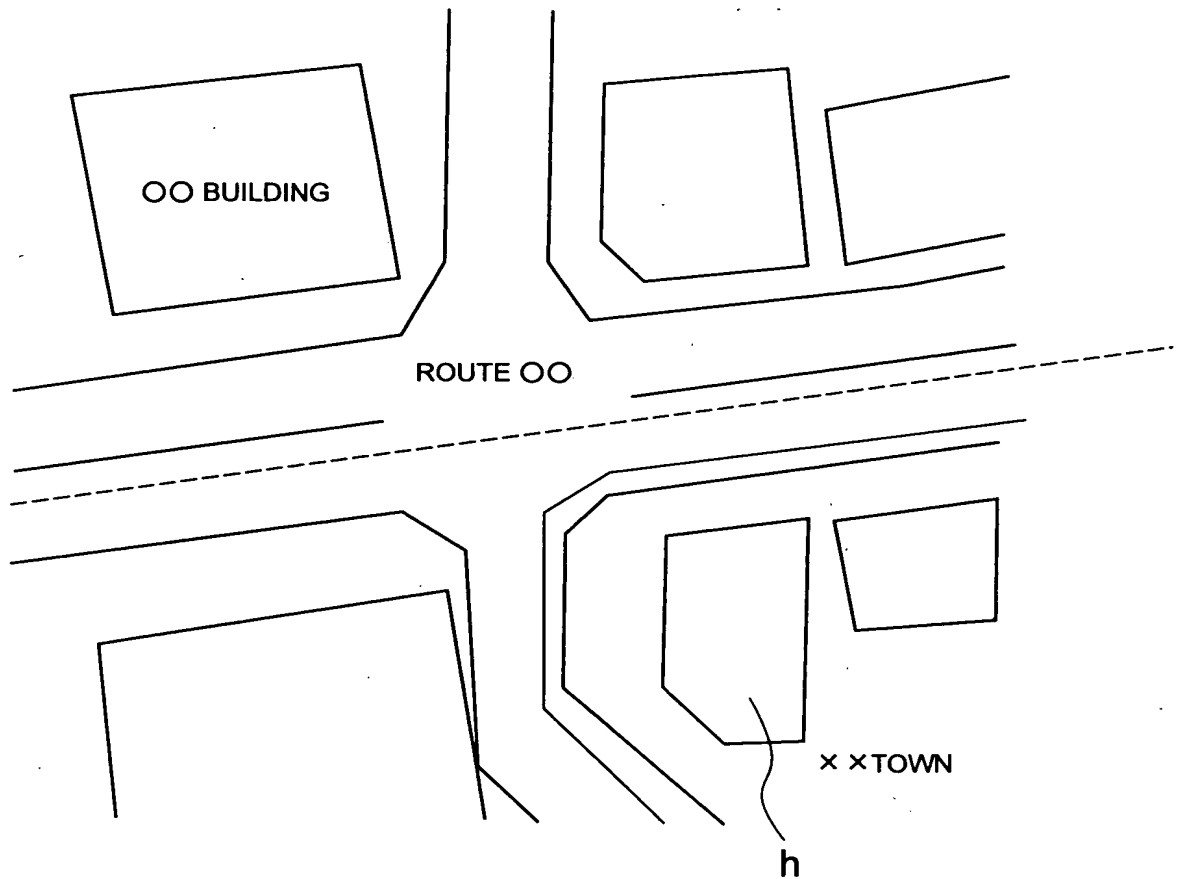
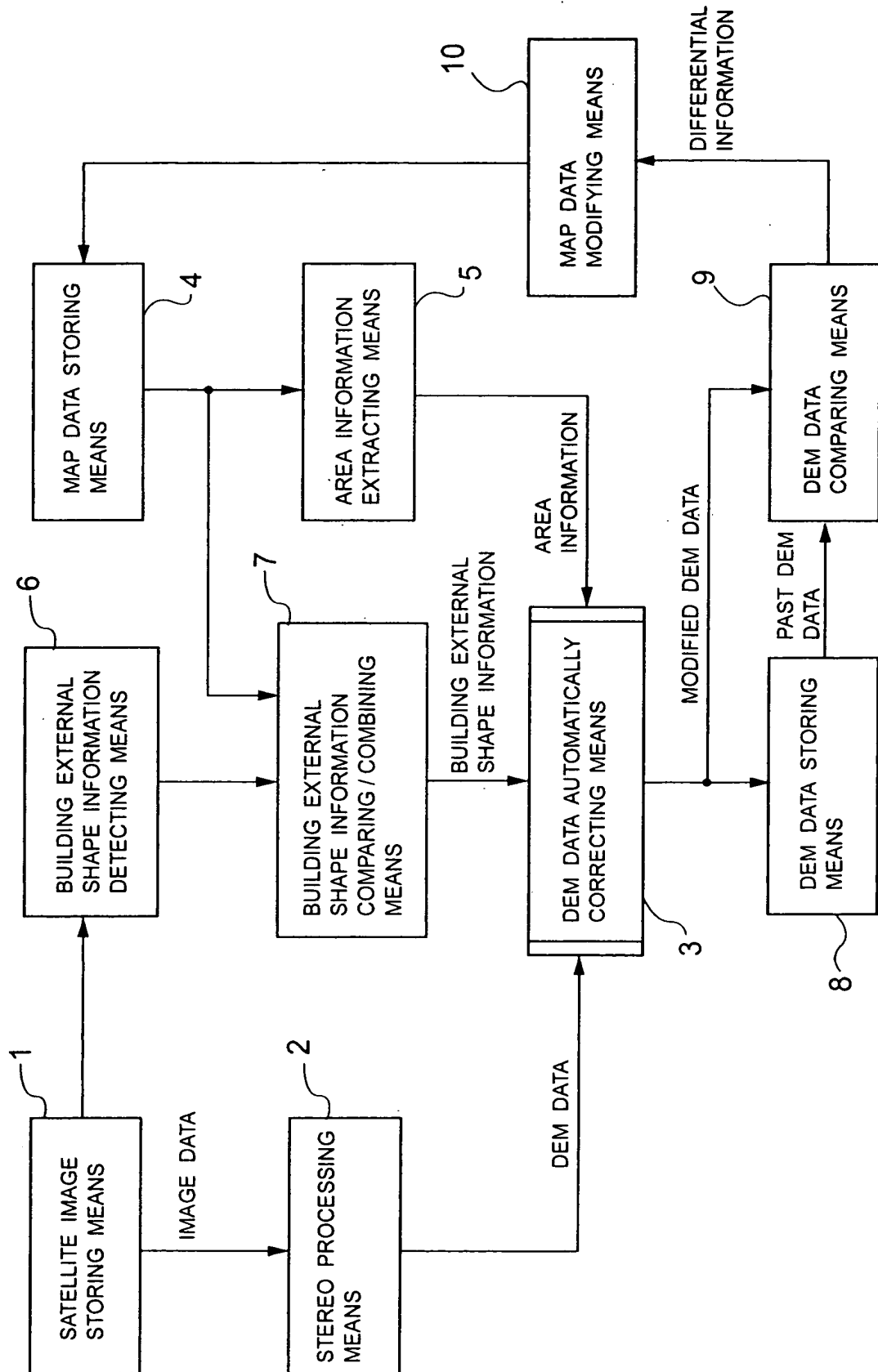


FIG. 39

42/46

FIG. 40



43/46

FIG. 41

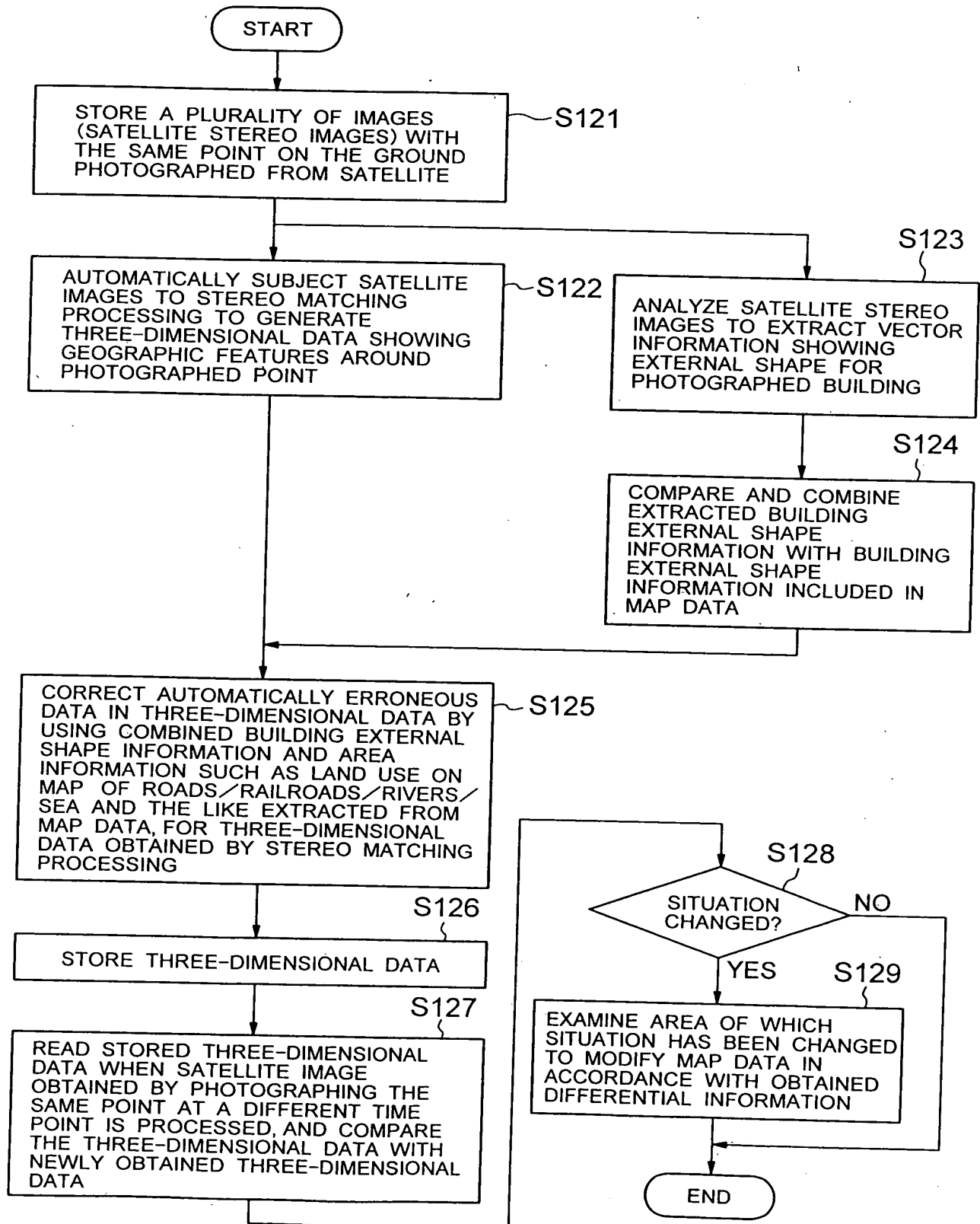
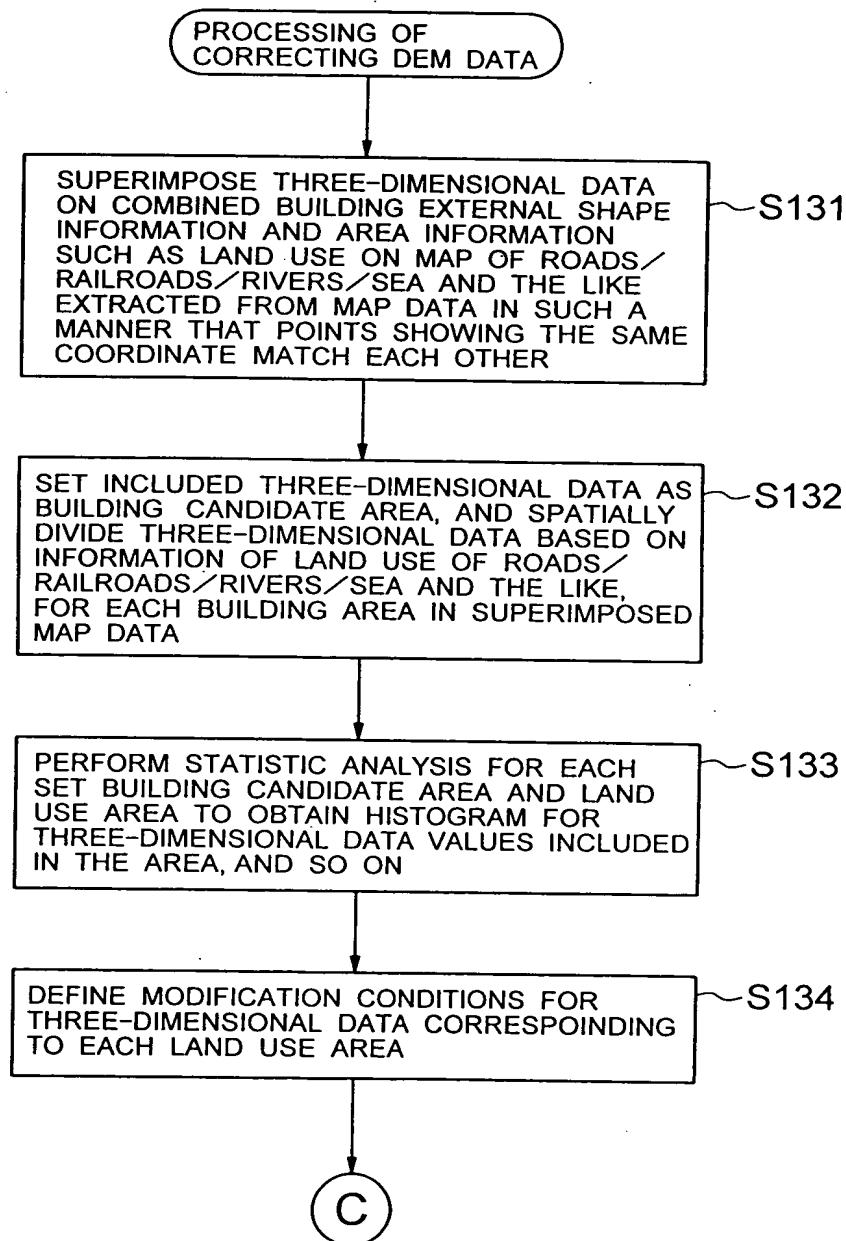
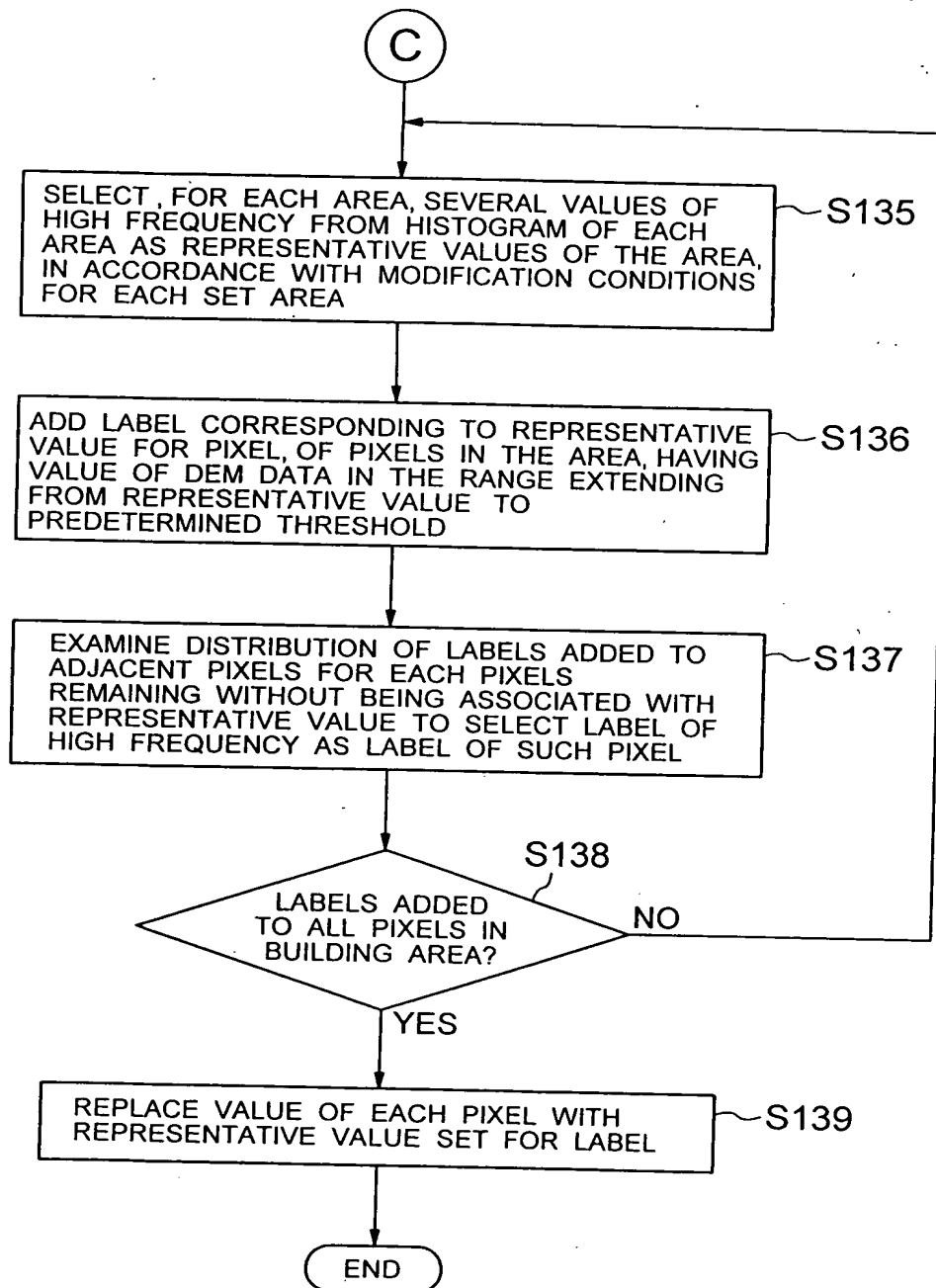


FIG. 42A



[illegible]

```
graph TD; 11[INPUT DEVICE] --> 12[DATA PROCESSING DEVICE]; 12 <--> 1[STORAGE DEVICE]; 12 <--> 4[MAP DATA STORING MEANS]; 14[RECORD MEDIUM] --> 12; 12 --> 15[OUTPUT DEVICE];
```

The diagram illustrates a data processing system. It features a central **DATA PROCESSING DEVICE** (12) which receives input from an **INPUT DEVICE** (11) and sends output to an **OUTPUT DEVICE** (15). The data processing device is connected to a **STORAGE DEVICE** (1) via a bidirectional arrow. The storage device contains two sub-components: **SATELLITE IMAGE STORING MEANS** (1) and **MAP DATA STORING MEANS** (4), both of which are connected to the data processing device via bidirectional arrows. Additionally, a **RECORD MEDIUM** (14) is connected to the data processing device via a bidirectional arrow.